

WCVALEACH: WEIGHT AND COVERAGE BASED ENERGY EFFICIENT ADVANCED LEACH ALGORITHM

Prof Ankit Thakkar¹ and Dr K Kotecha²

¹ Assistant Professor, Department of Computer Engineering, Institute of Technology,
Nirma University, Ahmedabad -382 481, Gujarat, India

ankit.thakkar@nirmauni.ac.in

² Director, Institute of Technology, Nirma University, Ahmedabad -382 481, Gujarat,
India

director.it@nirmauni.ac.in

ABSTRACT

Designing a protocol stack for wireless sensor network (WSN) is a challenging task due to energy, computational, communication and storage constraints. Energy spent for communication between sensor nodes dominates the energy spent for the computation [1]. Multi-hop short range communication between wireless sensor nodes is energy efficient compared to single-hop long range communication. Hierarchical clustering is one of the possible solutions to save energy of wireless sensor nodes. LEACH [16], Advanced LEACH (ALEACH)[14] and Weight based energy efficient Advanced LEACH (WALEACH) [20] are energy efficient hierarchical clustering routing protocols. In this paper we presented Weight and Coverage based Advanced LEACH routing protocol - WCVALEACH. WCVALEACH selects Cluster Head by assigning importance (weight) to different parameters used to select Cluster Head. It also creates the non-overlapped cluster regions to cover more number of member nodes. Both of these approaches makes WCVALEACH routing protocol energy efficient and improves life time of a wireless sensor network. Simulation results shown here verify that WCVALEACH not only improves network life time compared to ALEACH, LEACH and WALEACH algorithms but Packet Reception Rate (PRR) too.

KEYWORDS

Weight and Coverage based Advanced LEACH, Energy efficient, Wireless Sensor Network, Enhanced Packet Reception Rate (PRR), Clustering

1. INTRODUCTION

Wireless Sensor Network (WSN) getting popularity due to reduction in cost and size and advancement in Micro-Electro Mechanical System (MEMS). WSN getting attention due to their potential application in habitat monitoring system, forest fire detection, surveillance system, automated devices, structural health monitoring, Body Area Network (BAN) and other domains [2],[3]. Researchers getting interest in WSN because of many challenges and constraints associated with sensor networks which includes limited amount of energy, memory, communication and computational capabilities of a sensor node. To implement given task for a longer time, energy expenditure has to be done carefully by the sensor nodes. Energy required for communication is very high compared to computation and hence it should be carefully used to improve lifetime of a sensor network. Hierarchical clustering with data aggregation is one of the

solutions to enhance the life time of a sensor network [4][5][6][7]. In most applications of a sensor network, sensor nodes are dropped from the helicopter in a hostile environment and sensor nodes will automatically establish connection with the neighboring nodes. In WSN each sensor node not only generates sensed data and to process collected data but also acts as a router to send data to Base Station (BS) where end user can get useful information of his interest. In cluster based algorithm, nodes are grouped and form a cluster. One of the nodes within a cluster acts as a Cluster Head (CH) and other nodes within a cluster are called member nodes. Member nodes send their data to CH and CH forwards data to Sink node or Base Station (BS) directly or through other CHs using multi-hop communication.

Our algorithm is cluster based algorithm with the following objectives: To maximize the lifetime of a sensor network, to balance the energy depletion across the entire network and to enhance the Packet Reception Rate (PRR). Lifetime of a sensor network can be measured by three matrices: First Node Dies (FND), Half of the nodes Alive (HNA) and Last Node Dies (LND). In our protocol – WCVALEACH, we have introduced a new technique by assigning importance to different parameters to select the cluster head along with the creation of non-overlapping cluster region to make our algorithm energy efficient.

This paper is organized as follows: LEACH, ALEACH and WALEACH algorithms are discussed in Section 2, WCVALEACH algorithm is discussed in Section 3, Simulation results are presented in Section 4 and Concluding remarks are given in Section 5.

2. RELATED WORK

Energy being the most important constraint for WSN, now a days “Power Aware” routing techniques have been developed by many researcher [1], [8], [9], [10], [11], [12], [13]. In these techniques optimal routes are to be chosen which are energy-efficient and the node which is having highest energy will act as a cluster head. Our routing protocol, WALEACH, is also based on such technique by assigning weights to the different parameters used to select cluster head.

LEACH algorithm increases lifetime of the WSN by randomly rotating role of a CH among all the nodes. In LEACH, a node selects a random number between 0 and 1. If the selected random number is less than the threshold value $T(n)$, then node declares itself as a CH for the current round. Threshold value $T(n)$ is given by equation 1. LEACH ensures that each node becomes a cluster head only once in $1/p$ rounds, where p is a desired percentage of CH during each round. LEACH does not consider the current state (energy level) of a node while electing it as a CH.

$$T(n) = \begin{cases} \frac{p}{1-p*(r \bmod \frac{1}{p})} & \text{if } n \in G \\ 0 & \text{otherwise} \end{cases} \quad (1)$$

ALEACH [14] is distributed energy efficient routing protocol which considers energy level of a node while electing CHs. ALEACH doesn't require to know the locations of the nodes. Also, there is no need to do global communication to elect CH which is required in LEACH-C [15].

Like LEACH, ALEACH also works in rounds. Each round begins with Cluster Setup phase. During cluster setup phase a node will select a random number between 0 and 1. If selected random number is less than threshold value $T(n)$ then node will declare itself as a cluster head where $T(n)$ is given by equation 2.

$$T(n) = G_p + CS_p \quad (2)$$

where G_p and CS_p is given by equations 3 and 4 respectively. G_p and CS_p refer to general probability and current state probability.

$$G_p = \frac{k}{N - k * (r \bmod \frac{N}{k})} \quad (3)$$

where k/N refers to the desired percentage of cluster heads during each round and $E_{current}$ and E_{max} is remaining energy and maximum energy of a node respectively.

$$CS_p = \frac{E_{current}}{E_{max}} * \frac{k}{N} \quad (4)$$

ALEACH has considered energy level of a node to decide a node will become a CH during a particular round or not. Major drawback of ALEACH is proper importance (weights) is not given to general probability and current state probability. Main aim of our algorithm -WALEACH is to increase the lifetime of a WSN and increase the PRR by assigning proper weights to the general probability and current state probability.

WALEACH divides rounds into Cluster Set up phase and Steady Setup phase. Cluster Setup phase is used to elect cluster heads. During cluster setup phase each node selects a random number between 0 and 1. If selected number is less than threshold value $T(n)$, a node elects itself as a cluster head for the current round, where $T(n)$ is given by equation 2. The general probability and current state probability is given by equation 5 and equation 6 respectively. In these equations w is used to assign weight (importance) to general probability and current state probability.

$$G_p = \frac{N - (w * k)}{N} * \frac{k}{N - k * (r \bmod \frac{N}{k})} \quad (5)$$

$$CS_p = \frac{w * k}{N} * \frac{E_{current}}{E_{max}} \quad (6)$$

CVLEACH[21] is a Coverage based LEACH algorithm. It creates non-overlapping cluster regions to cover more member nodes by the cluster heads to conserve energy of nodes and enhances life time of a sensor network.

3. WCVALEACH: WEIGHT AND COVERAGE BASED ADVANCED LEACH ROUTING PROTOCOL

ALEACH has considered energy level of a node to decide a node will become a CH during a particular round or not. Major drawback of ALEACH is proper importance (weight) is not given to general probability and current state probability. WALEACH assigns importance to general probability and current state probability. Main aim of our algorithm - WCVALEACH is to increase the lifetime of a WSN and to increase PRR by assigning proper weights to the general probability and current state probability. It also creates non-overlapping cluster regions as does in CVLEACH [21] to further increase the lifetime of WSN.

WCVALEACH divides rounds into Cluster Set up phase and Steady Setup phase. Cluster Setup phase is used to elect cluster heads. During cluster setup phase each node selects a random number between 0 and 1. If selected number is less than threshold value $T(n)$, a node elects itself as a cluster head for the current round, where $T(n)$ is given by equation 2. The general probability and current state probability is given by equation 5 and equation 6 respectively. In these equations w is used to assign weight (importance) to general probability and current state probability.

When any node receives Cluster Head announcement, it withdraws its participation to be elected as a cluster head for the current round. This helps to create non-overlapping cluster regions, and covers more number of member nodes. Cluster Set up phase of WCVALEACH algorithm is shown in Algorithm 1 and Steady Set up phase is shown in Algorithm 2 which is used by member nodes to send data to their cluster heads.

Algorithm 1 Cluster Set up Phase

Require: *Total Round Time* > 0 and *Round Duration* > 0 and *Total Round Time* / *Round Duration* and $N > 0$ and $0 < P < 1$

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1: for all nodes  $i \in N$  do
2: ClusterHeadInLastRound = false
3: end for
4: rounds =  $\lfloor (\text{SimulationTime} / \text{RoundTime}) \rfloor$ 
5: for  $r = 0$  to rounds - 1 do
6: for all nodes  $i \in N$  do
7: if ClusterHeadInLastRound then
8:  $T(i) = 0$ 
9: StartJoinTimer( $i$ )
10: Wait_For_CH_Advertisement( $t$ )
11: if CHAdvReceived then
12: Send_Join_Request( $i$ )
13: Wait_For_TDMA_Schedule( $t$ )
14: end if
15: else
16: if  $T(i) > \text{random}(0, 1)$  and not CHAdvReceived then
17: ClusterHeadInLastRound = true
18: Do_Cluster_Head_Announcement( $i$ )
19: Wait_For_Join_Request( $t$ )
20: for all  $j \in \text{Members}$  do
21: Send_TDMA_Schedule( $j$ )
22: end for
23: else
24: StartJoinTimer( $i$ )
25: Wait_For_CH_Advertisement( $t$ )
26: if CHAdvReceived then
27: Send_Join_Request( $i$ )
28: Wait_For_TDMA_Schedule( $t$ )
29: end if
30: end if
31: end if
32: CallAlgorithm2( $i$ )
33: end for
34: if  $(\text{round} + 1) = \lfloor N / (P * 100) \rfloor$  then
35: ClusterHeadInLastRound = false
36: end if
37: end for

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Algorithm 2 Steady-State Phase

Require: i 1: **if** $t < RoundTime$ **then**2: **if** $i \in CH$ **then**3: **for all** $j \in Members(i)$ **do**4: *Collect_Data_From_Member_Nodes(j)*5: **end for**6: *Send_Aggregate_Data_To_Sink_By_CH(i)*7: **else**8: **if** $t < Scheduled\ Start\ Time$ or $t > Scheduled\ End\ Time$ **then**9: *Sleep_Node(i)*10: **else**11: *Send_Data_To_CH_By_Member(i)*12: **end if**13: **end if**14: **end if**

4. RESULTS AND DISCUSSION

The network model used in WCVALEACH is having following properties as mentioned in [14],[15],[16],[17],[20].

- BS consists of high level of energy and located far away from sensor nodes.
- All nodes within the network are immobile.
- All nodes are uniform.
- Each node is able to control its transmission power as and when required.
- Each node sense environment at a fixed rate and have some data to send to BS or CH.

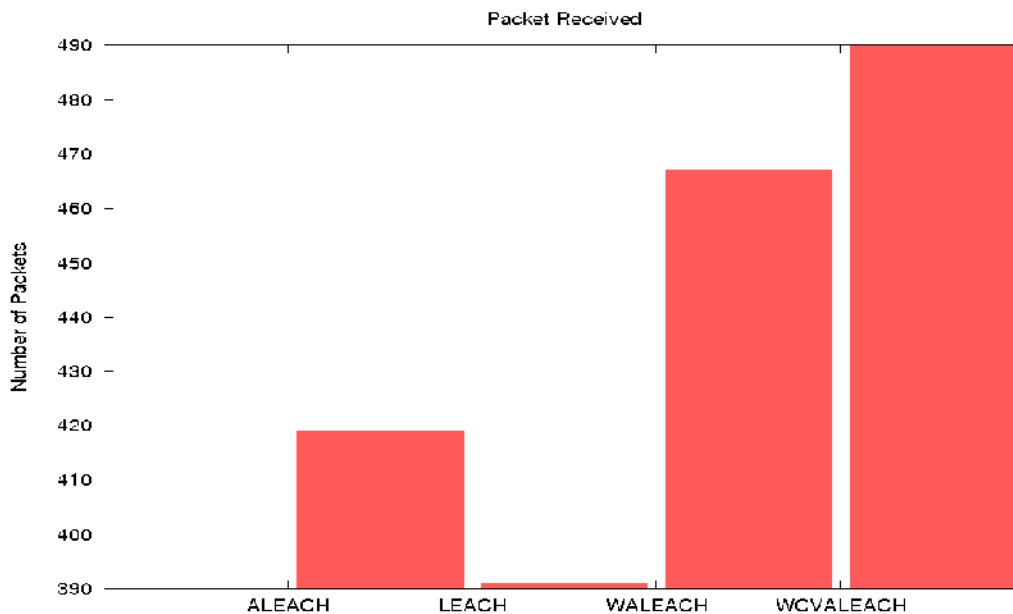


Figure 1. Number of Packets Received

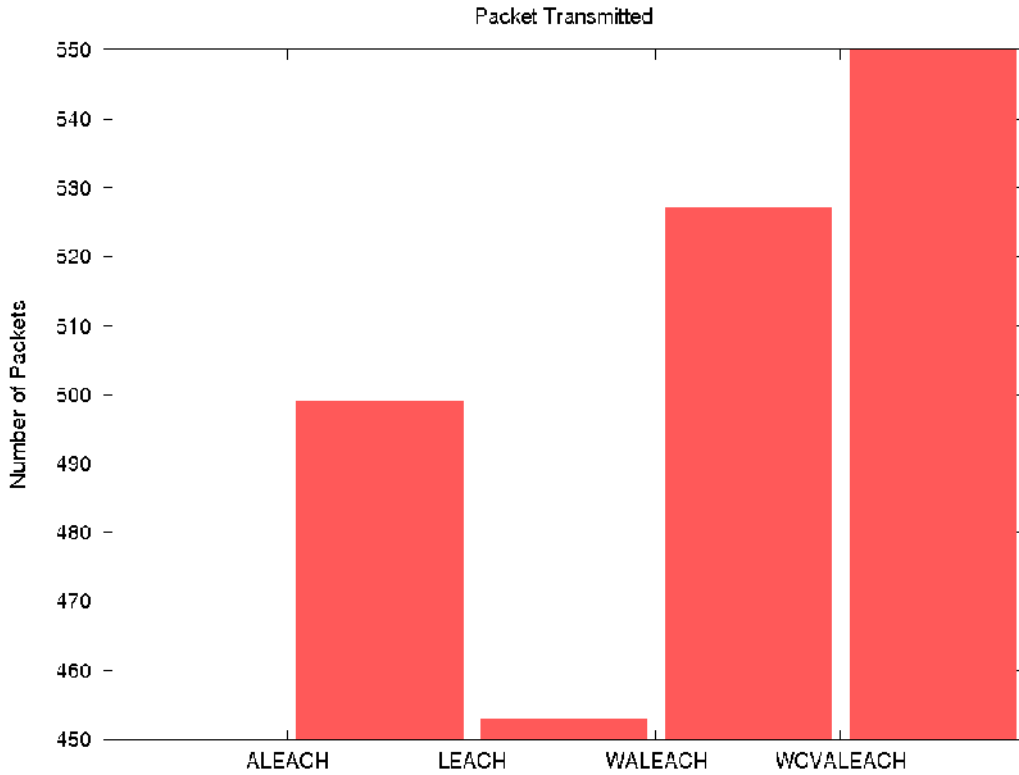


Figure 2. Number of Packets Transmitted

We have investigated performance of WCVALEACH against LEACH, ALEACH and WALEACH algorithm using Castalia simulator [18]. Castalia can be used for simulation of Wireless Sensor Networks (WSN), Body Area Networks (BAN) and networks of low-power embedded devices. It is used to test distributed algorithms and/or protocols in realistic wireless channel and radio models, with a realistic node behavior especially relating to access of the radio [18]. A network of size 500mx 500m is created with randomly distributed 100 sensor nodes to test performance of WALEACH against LEACH and ALEACH. Each node has CC2420 as transceiver. Each node constantly draws 6mW and sensing device within the node draws 0.02mW. The transceiver energy parameters are set as: $E_{Tx} = 46.2mW$ to do cluster head announcement, to send cluster join message and to send data by member nodes to their respective cluster heads; $E_{Tx} = 57.42mW$ to send data by the non cluster member nodes and cluster heads to Base Station. A transceiver of node can be in one of the three states: RX (receive), TX (transmit) or SLEEP, if node is alive. Transceiver takes the 194 μ sec to change from SLEEP state to either RX or TX, 10 μ sec to change between TX and RX states and 50 μ sec to enter the SLEEP state [18]. Transition to SLEEP state from RX or TX consumes 1.4mW while any other transition consumes 62mW [18].

Table 1. Simulation Parameters

Parameter	Value
Node Deployment Area	500m x 500m
Number of Nodes	100
Initial Energy	18720 Joules
Energy to do CH announcement	46.2mW
Energy to transmit data to CH	
Energy to send CH Join Message	
Energy to transmit BS	57.42mW
Rate of Sensory Data generation	Every 2 Seconds
Round Duration	20 Seconds
Simulation Time	1000 Seconds
Operating power of a Node	6mW
Operating power of a sensing device	0.02mW
Size of Control and Data messages	30 Bytes
Expected percentage of CH per round	5%
Weight Factor (w)	3.81
Initial Energy (for FND,HND,LND)	6 Joules

Size of control and data message is set to 30 bytes. Every 2-seconds sensor will report sensed data to the node itself. Round time is fixed to 20-seconds. Each node has given 18720 Joules of initial energy which is equivalent to energy of two AA batteries [18]. p is set to 5% in Equation 1. w is set to 3.81 in Equations 5 and 6. This value of w gives optimal performance of WALEACH and WCVALEACH. This value of w is verified through experiments. Simulation parameters is listed in Table 1.

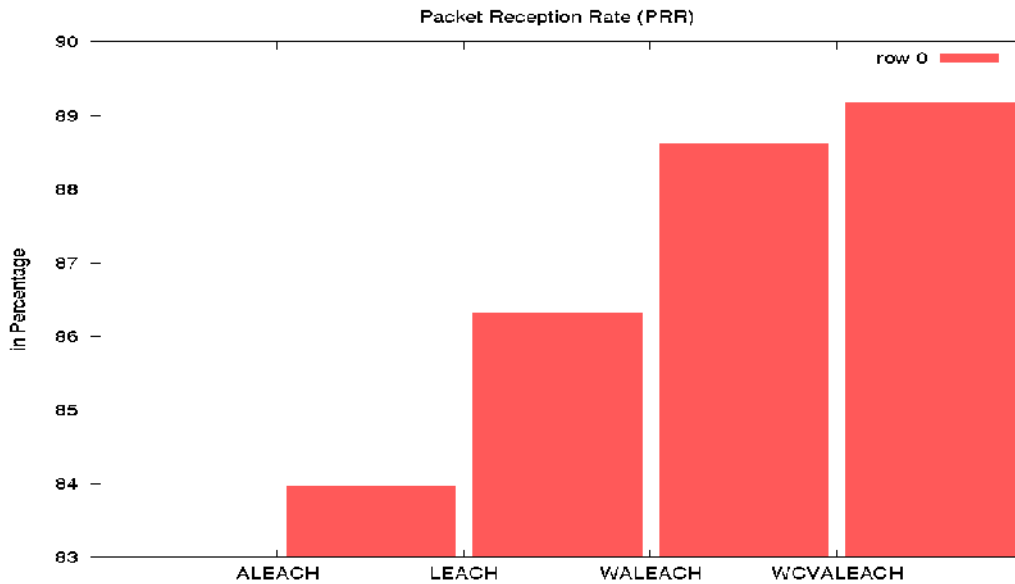


Figure 3. Packet Reception Rate (in Percentage)

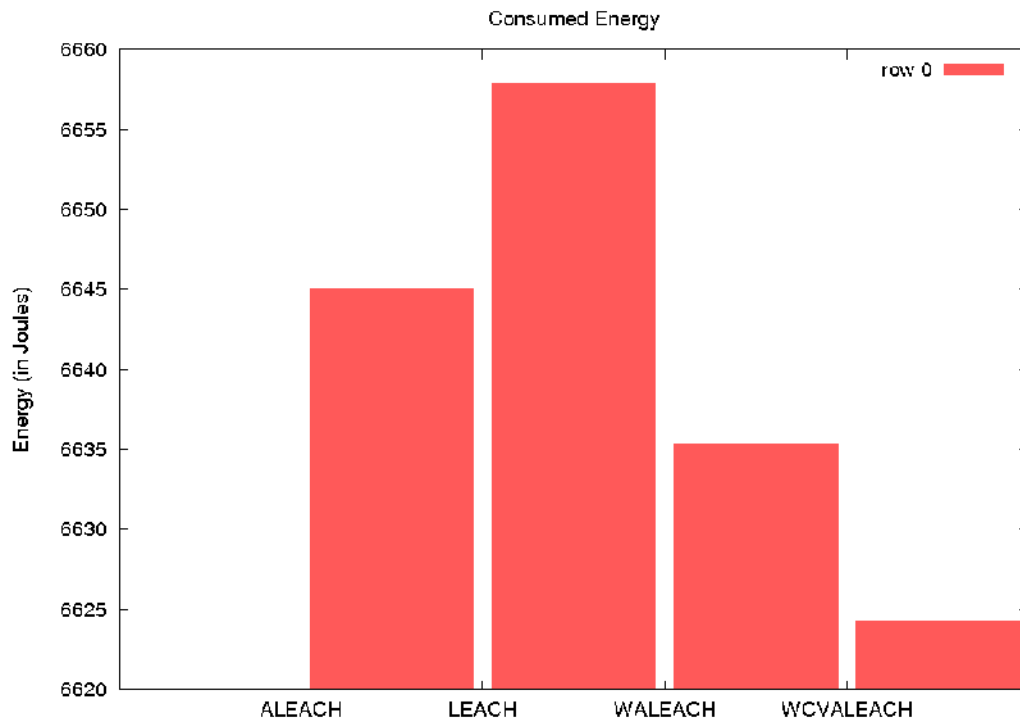


Figure 4. Total Energy Consumption (in Joules)

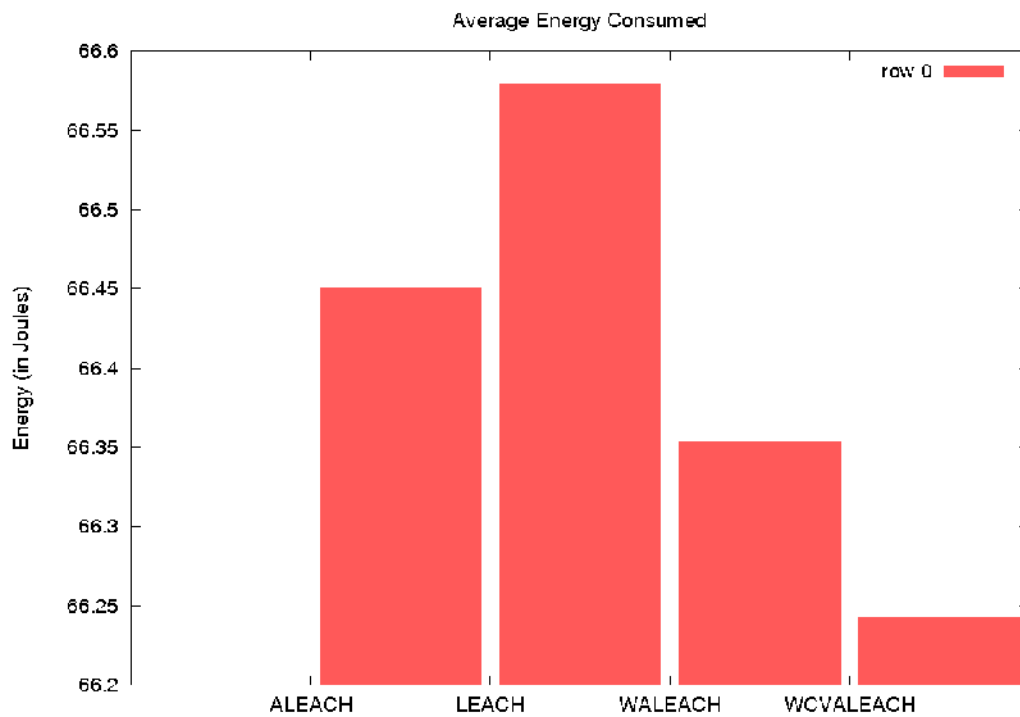


Figure 5. Average Energy Consumption per Node (in Joules)

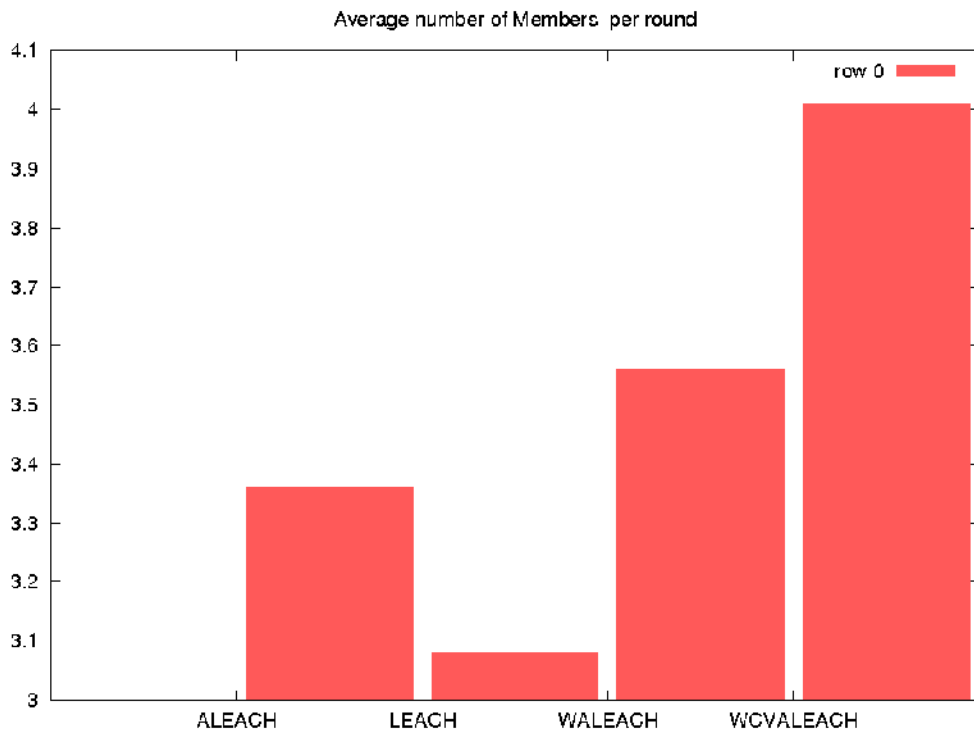


Figure 6. Average Number of Member Nodes per Round

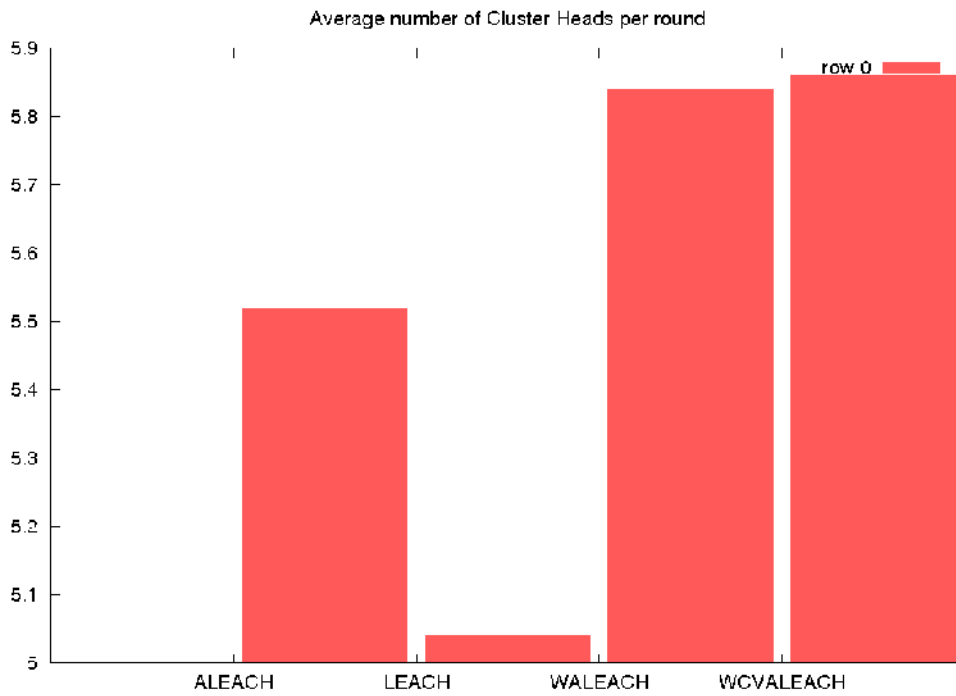


Figure 7. Average Number of Cluster Heads per Round

We have run simulation for 1000 seconds to investigate following performance metrics: Packet Reception Rate: It represents the ratio of number of packet received over number of packet transmitted; Energy consumption: It represents total energy consumption of all nodes, and Average energy consumption per node: It represents the average energy expenditure of a node. Coverage: Average number of members covered by all cluster heads per round; Fitness of Cluster Head: It represents average number of cluster heads; Network Life Time: Network life time can be measured in terms of First Node Dies (FND), Half of the Nodes Alive (HNA) and Last Node Dies (LND) and total life time of all nodes. Total number of packets received and transmitted is shown in figure 1 and 2 respectively. Total packets received for LEACH, ALEACH, WALEACH and WCVLEACH are 391, 419, 467 and 490 while total packets transmitted for LEACH, ALEACH, WALEACH and WCVLEACH are 453, 499, 527 and 550 respectively. Packet reception rate for LEACH, ALEACH, WALEACH and WCVLEACH is found 86.314%, 83.968%, 88.615% and 89.09% respectively and is shown in Figure 3. Total energy consumption of all nodes and average energy consumption per node for LEACH, ALEACH, WALEACH and WCVLEACH is shown in figures 4 and 5 respectively. Total energy consumption of all nodes is 6657.897 Joules, 6645.132 Joules, 6636.108 Joules and 6624.264 Joules and average energy consumption per node is 66.579 Joules, 66.451 Joules, 66.361 Joules and 66.243 Joules recorded for LEACH, ALEACH, WALEACH and WCVLEACH algorithm respectively. For the simulation, p is set to 5% in equation 1 and w is set to 3.81 in equations 5 and 6. Number of nodes which are covered by the cluster heads and average number of cluster heads is shown in Figure 6 and Figure 7 respectively. An average member of all clusters during each round is shown in Figure 6 and it is 3.08, 3.36, 3.56 and 4.01 for LEACH, ALEACH, WALEACH and WCVLEACH algorithm. It can be seen from Figure 7 that average number of cluster heads per round for LEACH, ALEACH, WALEACH and WCVLEACH is 5.04, 5.52, 5.84 and 5.86. Energy required to communicate with cluster heads is very less compared to energy required to communicate with base station. Hence, energy conservation for WCVLEACH is better than ALEACH, LEACH and WALEACH algorithms.

There are three major matrices which can be used to measure lifetime of sensor nodes: First Node Dies - FND, Half of the Nodes Alive - HNA, and Last Node Dies - LND [19]. To test these matrices, 6 Joules of initial energy is given to each node and FND, HNA and LND recorded for LEACH, ALEACH, WALEACH and WCVLEACH which is shown in Table 2. It can be seen from the Table 2 that WCVLEACH is better than LEACH, ALEACH and WALEACH algorithms in terms of FND, HNA and LND. Total life time all the nodes of WCVLEACH is 4.867% better than LEACH, 3.954% better than ALEACH and 1.848% better than WALEACH when only 6 Joules of initial energy is given to each node. Comparative of performance matrices simulated for ALEACH, WALEACH, LEACH and WCVLEACH is shown in Table 3.

Table 2. FND, HNA, LND and Network life time (initial Energy 6 Joules/Node)

Algorithm	FND (in Seconds)	HNA (in Seconds)	LND (in Seconds)	Network Life Time (in Seconds)
ALEACH	88.248	89.076	103.677	9176.344
WALEACH	88.268	88.999	116.169	9377.580
LEACH	88.243	88.855	103.710	9089.122
WCVLEACH	88.273	90.509	127.242	9554.150

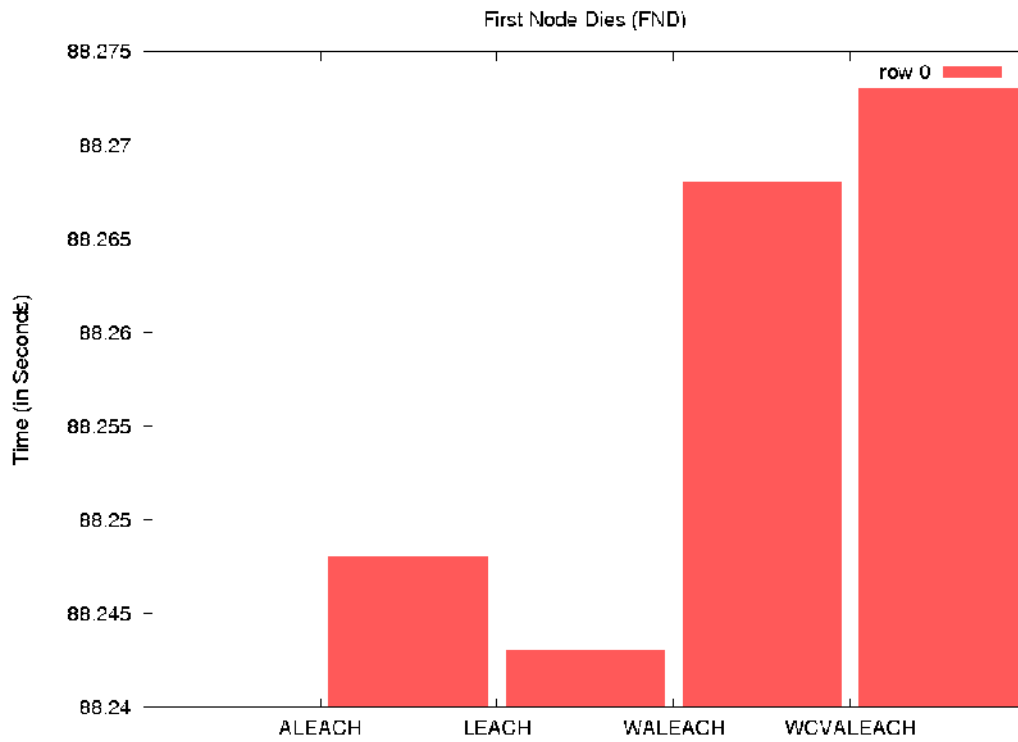


Figure 9. First Node Dies (FND)

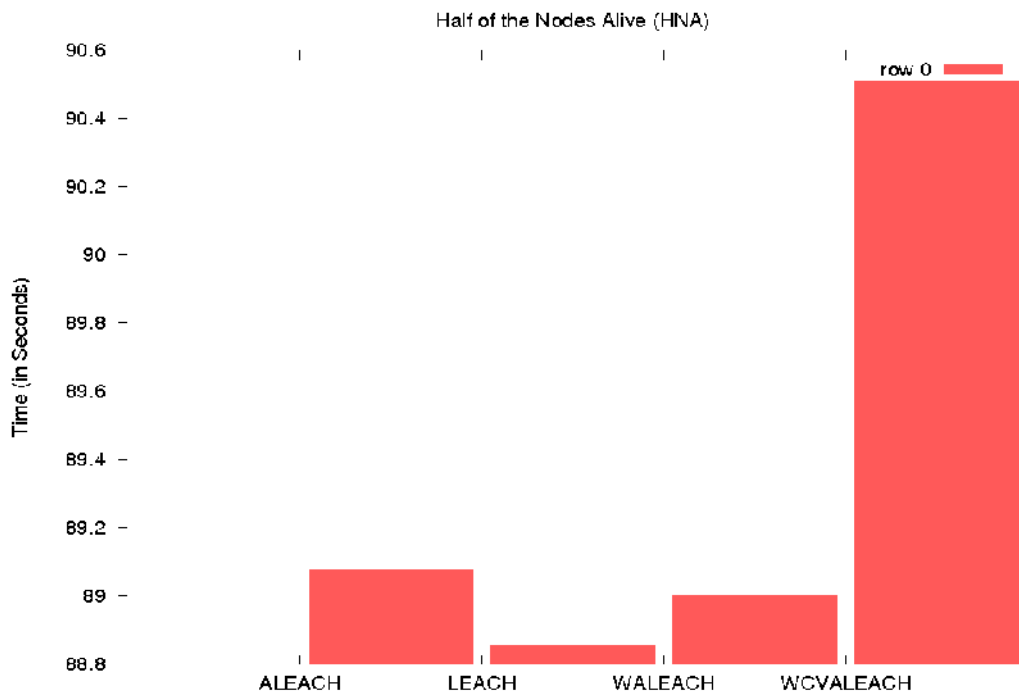


Figure 10. Half of the Nodes Alive (HNA)

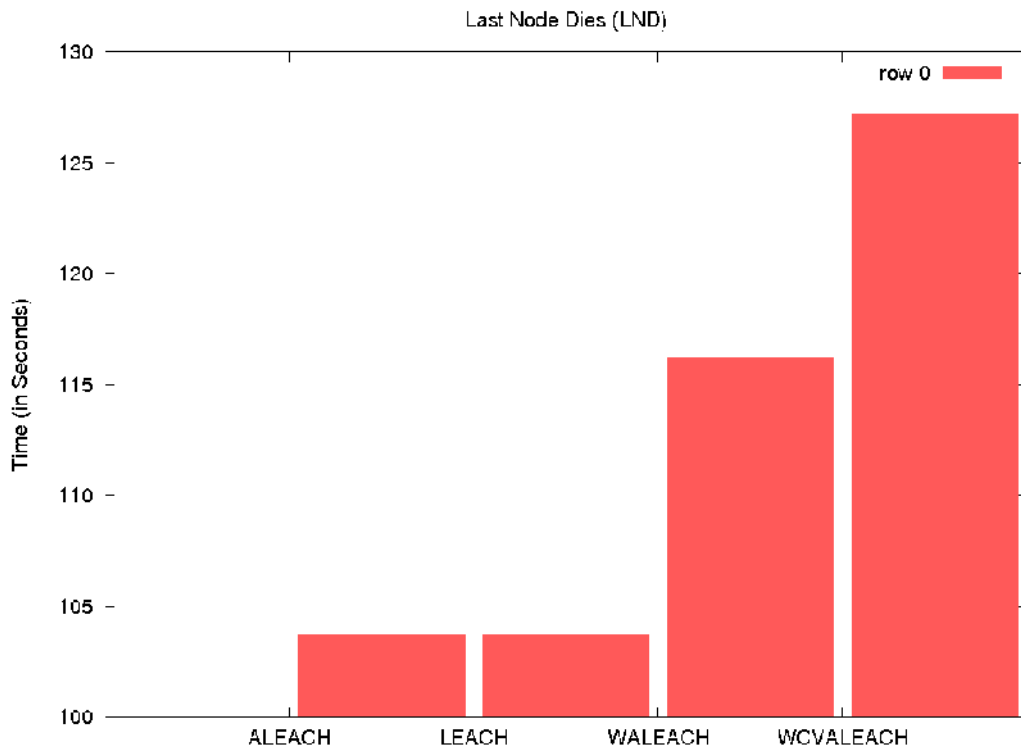


Figure 11. Last Node Dies (LND)

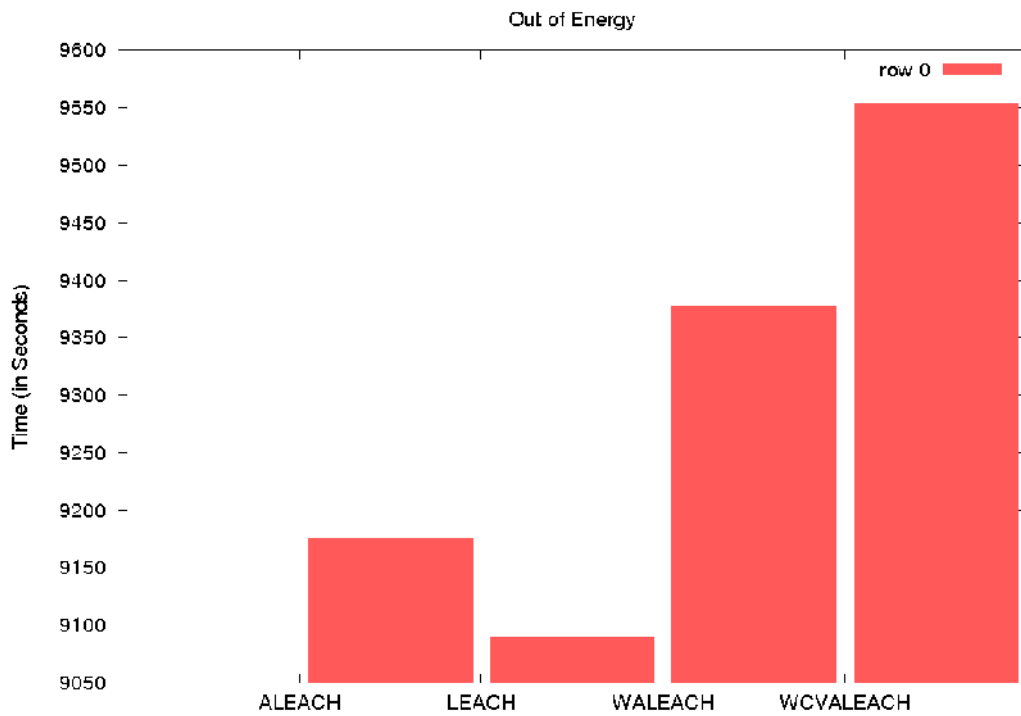


Figure 12. Total Life Time of the Network with Initial Energy 6 Joules/Node

Table 3. Comparative of Performance Matrices

Performance Matrix	LEACH	ALEACH	WALEACH	WCVALEACH
Number of Packets Transmitted	453	499	527	550
Number of Packets Received	391	419	467	490
Packet Reception Rate	86.314%	83.968%	88.615%	89.09%
Total Energy Consumption	6657.897 Joules	6645.132 Joules	6636.108 Joules	6624.264 Joules
Average Energy Consumption per Node	66.579 Joules	66.451 Joules	66.361 Joules	66.243 Joules
Average Number of Cluster Heads per Round	5.04	5.52	5.84	5.86
Average Number of Members per Round	3.08	3.36	3.56	4.01

5. CONCLUSION

WCVALEACH is distributed and energy efficient algorithm. Neither it requires location information of a node nor does it require exchange of communication messages to decide the Cluster Head. It increases the lifetime of a sensor network which we have verified using FND, HNA and LND matrices. It also increases Packet Reception Rate (PRR). WCVALEACH does energy conservation by assigning weight as WALEACH and by creating non-overlapping cluster regions as CVLEACH.

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Authors

Prof Ankit Thakkar – is working as Assistant Professor at Institute of Technology, Nirma University, Ahmedabad – 382 481, Gujarat, India. He is pursuing Ph. D. in the area of Wireless Sensor Networks. He has received "Gold Medal" for securing highest CPI among all graduating students of M.Tech. Computer Science & Engineering 2007-09 batch from Institute of Technology, Nirma University, Ahmedabad. His area of interest includes Wireless Sensor Networks, Embedded Systems, Image Processing, Real-time Systems and Data Structures and Algorithms.

Dr K Kotecha – is working as Director, Institute of Technology, Nirma University, Ahmedabad -382 481, Gujarat, India. He did his M.Tech. and Ph.D. from IIT, Bombay. His area of interest includes Analysis of Algorithms, Optimization Techniques and Sensor Networks