SCOPE OF THE JOURNAL

The International Journal of Chaos, Control, Modelling and Simulation is a bi-monthly open access peer-reviewed journal that publishes articles which contribute new results in all areas of Chaos Theory, Control Systems, Scientific Modelling and Computer Simulation. In the last few decades, chaos theory has found important applications in secure communication devices and secure data encryption. Control methods are very useful in several applied areas like Chaos, Automation, Communication, Robotics, Power Systems, and Biomedical Instrumentation. The journal focuses on all technical and practical aspects of Chaos, Control, Modelling and Simulation.

Authors are solicited to contribute to this journal by submitting articles that illustrate research results, projects, surveying works and industrial experiences that describe significant advances in Chaos Theory, Control Systems, Modelling and Simulation Technique.

Areas and subareas of interest include (but are not limited to):

- Adaptive control
- Advanced chaos theory
- Advanced computing techniques
- Algorithms, modelling and simulation
- Applications of chaos in science and engineering
- Artificial intelligence
- Artificial neural networks
- Automation and mobile robots
- Bioinformatics
- Biological modelling
- Biological systems and models
- Chaotic systems
- Chaos modelling
- Circuit realization of chaotic systems
- Control of chaotic systems
- Cloud computing
- Communication engineering
- Computational biology
- Computational fluid dynamics
- Computer science
- Control devices & instruments
- Control theory
- Data mining
- Data Structures and Algorithms
- Scientific computing
- Secure communication devices
- Stochastic modelling and control
- Data visualization
- Digital control
- Digital image processing
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- Dynamical systems and stability theory
- Embedded systems and control
- Evolutionary techniques in engineering
- Flight control and surveillance systems
- Fuzzy logic control
- Genetic algorithms and applications
- Hyperchaotic systems
- Industrial applications of control
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- Mathematical control theory
- Mathematical modelling and applications
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- Nonlinear control theory
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- Robust control
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