Bayesian system reliability and availability analysis underthe vague environment based on Exponential distribution

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Abstract

Reliability modeling is the most important discipline of reliable engineering. The main purpose of this paper is to provide a methodology for discussing the vague environment. Actually we discuss on Bayesian system reliability and availability analysis on the vague environment based on Exponential distribution under squared error symmetric and precautionary asymmetric loss functions. In order to apply the Bayesian approach, model parameters are assumed to be vague random variables with vague prior distributions. This approach will be used to create the vague Bayes estimate of system reliability and availability by introducing and applying a theorem called "Resolution Identity" for vague sets. For this purpose, the original problem is transformed into a nonlinear programming problem which is then divided up into eight subproblems to simplify computations. Finally, the results obtained for the subproblems can be used to determine the membership functions of the vague Bayes estimate of system reliability. Finally, the sub problems can be solved by using any commercial optimizers, e.g. GAMS or LINGO.

Keywords: Bayes point estimators, Vague environment, Nonlinear programming; System reliability, System availability, Exponential distribution, Precautionary loss function.

1. Introduction

In the real world there are vaguely specified data values in many applications, such as sensor information. Fuzzy set theory has been proposed to handle such vagueness by generalizing the notion of membership in a set. Essentially, in a fuzzy set each element is associated with a point-value selected from the unit interval [0,1], which is termed the grade of membership in the set. A vague set, as well as an Intuitionistic fuzzy set, is a further generalization of a fuzzy set. Instead of using point-based membership as in fuzzy sets, interval-based membership issued in a vague set.Gau and Buehrer (1993) define vague sets. These sets are used by Shyi-Ming Chen and Jiann-Mean Tan (1994). Once the vague (intuitionistic fuzzy) set theory have been introduced, a number of authors investigated the reliability analysis in vague set theory, where the reliabilities of system components are represented by vague sets. Kumar et al. (2006) developed a method for

¹- Ramin.gholizadh@gmail.com ²- Zayrsil@gmail.com DOI : 10.5121/ijsc.2012.3103 analyzing system reliability by using interval-valued vague sets, and applied it for the reliability analysis of a Marine Power Plant.

Complex systems may have both kinds of uncertainty. Researchers have stated that probability theory can be used in concert with fuzzy set theory for the modeling of complex systems Zadeh (1995), Barrett and Woodall (1997), Ross, Booker, and Parkinson (2003), and Singpurwalla and Booker (2004). Bayesian statistics provide a natural framework combining random and nonrandom uncertainty so fuzzy Bayesian methods are developed for the solutions of the reliability problems. Sellers and Singpurwalla (2008) addressed the reliability of multistate systems with imprecise state classification. On the other hand, Gholizadeh, Shirazi, Gildeh, and Deiri (2010), Gholizadeh, Shirazi, and Gildeh (2010), Görkemli and Ulusoy (2010), Huang, Zuo, and Sun (2006), Taheri and Zarei (2011), Viertl (2009), and Wu (2004, 2006) addressed the problem of imprecise data (approximately recorded failure time durations and number of failures) in reliability studies.

Fuzzy Bayesian reliability method developed by Wu (2004, 2006). Taheri and Zarei (2011) modeled and evaluated Bayesian system reliability considering the vague environment. Our modeling approach is a generalization of Wu (2004, 2006) and Taheri and Zarei (2011).

Vague environment is introduced in Section 2. Vague point estimator is represented in Section 3. In Section 4, the reliability and availability analysis via vague Bayesian method under squared error and precautionary loss functions for series system, parallel system and k-out-of-n system have been discussed is illustrated on an example. The computational procedures and examples are provided in order to clarify the theory discussed in this paper, and to give a possible insight for applying the vague set to Bayesian system reliability and availability. Conclusions and future extensions of this work are given in Section 6.

2. Vague environment

Definition 1. A vague set \tilde{V} in a universe of discourse U is characterized by a true membership function, $t_{\tilde{V}}$, and a false membership function, $f_{\tilde{V}}$, as follows: $t_{\tilde{V}} \quad U \quad [0,1], f_{\tilde{V}} \quad U \quad [0,1],$ and $t_{\tilde{V}}(u) + f_{\tilde{V}}(u) = 1$, where $t_{\tilde{V}}(u)$ is a lower bound on the grade of membership of u derived from the evidence for u, and $f_{\tilde{V}}(u)$ is a lower bound on the grade of membership of the negation of u derived from the evidence against u.

Suppose $U = \{u_1, u_2, ..., u_n\}$ A vague set \tilde{V} of the universe of discourse U can be represented by $\tilde{V} = \prod_{i=1}^{n} [t_{\tilde{V}}(u_i), 1 - f_{\tilde{V}}(u_i)]/u_i$, where $0 \quad t(u_i) \quad 1 - f(u_i) \quad 1 \text{ and } 1 \quad i \quad n$. In other words, the grade of membership of u_i is bounded to a subinterval $[t(u_i), 1 - f_{\tilde{V}}(u_i)]/u_i$ of [0, 1]. Thus, vague sets are a generalization of Fuzzy sets, since the grade of membership $\mu_{\tilde{V}}(u)$ of u in Definition 1 may be inexact in a vague set. We now depict a vague set in Fig. 1.

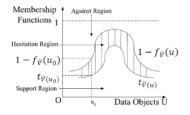


Fig. 1. Membership Functions of a vague set.

Definition 2. The complement of a vague set \tilde{V} is denoted by \tilde{V}' and is defined by

$$t_{\widetilde{V}'}(u) = f_{\widetilde{V}}(u),$$

$$1 - f_{\widetilde{V}'}(u) = 1 - f_{\widetilde{V}'}(u).$$

Definition 3. A vague set \tilde{V}_A is contained in another vague set \tilde{V}_B , $\tilde{V}_A = \tilde{V}_B$, if and only if,

$$t_{\widetilde{V}_A}(u) = t_{\widetilde{V}_B}(u),$$

 $1 - f_{\widetilde{V}_A}(u) = 1 - f_{\widetilde{V}_B}(u).$

Definition 4. Two vague sets \tilde{V}_A and \tilde{V}_B are equal, written as $\tilde{V}_A = \tilde{V}_B$, if and only if, $\tilde{V}_A = \tilde{V}_B$ and $\tilde{V}_B = \tilde{V}_A$; that is

$$t_{\widetilde{V}_A}(u) = t_{\widetilde{V}_B}(u),$$

1 - $f_{\widetilde{V}_A}(u) = 1 - f_{\widetilde{V}_B}(u).$

Definition 5.Let $\tilde{V}_{t_{\tilde{V}},f_{\tilde{V}}}$ be a vague set of U. Then, we define α_t -cuts and α_f -cuts of \tilde{V} as the crisp sets of U given by

$$\begin{split} \tilde{V}_{\alpha_t} &= \{ u \ t_{\widetilde{V}}(u) \ \alpha_t \}, \quad \alpha_t \ [0,1], \\ \tilde{V}_{\alpha_f} &= \{ u \ 1 - f_{\widetilde{V}}(u) \ \alpha_f \}, \quad \alpha_f \ [0,1], \end{split}$$

Definition 6.Let $\tilde{V}_{t_{\tilde{V}},f_{\tilde{V}}}$ be a vague set of $U = \mathcal{R}$. We say that \tilde{V} is convex if for all $u_1, u_2 = U$ and λ in [0,1],

$$t_{\widetilde{V}}(\lambda u_1 + (1 - \lambda)u_2) \quad \min(t_{\widetilde{V}}(u_1), t_{\widetilde{V}}(u_2)),$$

$$1 - f_{\widetilde{V}}(\lambda u_1 + (1 - \lambda)u_2) \quad \min(1 - f_{\widetilde{V}}(u_1), 1 - f_{\widetilde{V}}(u_2)).$$

Definition 7. A vague set $\tilde{V}_{t_{\tilde{V}},f_{\tilde{V}}}$ of \mathcal{R} with continuous membership functions $t_{\tilde{V}}$ and $f_{\tilde{V}}$ is called a vague number if and only if \tilde{V}_{α_t} and \tilde{V}_{α_f} , for all α_t, α_f (0, 1], are bounded closed intervals; i.e.

$$\begin{split} \widetilde{V}_{\alpha_t} &= \left[\widetilde{V}_{\alpha_t}^L, \widetilde{V}_{\alpha_t}^U \right] \\ \widetilde{V}_{\alpha_f} &= \left[\widetilde{V}_{\alpha_f}^L, \widetilde{V}_{\alpha_f}^U \right] \end{split}$$

We denote the class of all vague numbers by $V(\mathcal{R})$.

Definition 8. The vague number $\tilde{V}_{t_{\tilde{v}},f_{\tilde{v}}}$ is called a triangular vague number, if

$$t_{\widetilde{V}}(u) = \begin{cases} \frac{u-a_1}{w(a_2-a_1)} & a_1 & u & a_2 \\ \frac{a_3-u}{w(a_3-a_2)} & a_2 & u & a_3 \\ 0 & otherwise \end{cases}$$
$$1 - f_{\widetilde{V}}(u) = \begin{cases} \frac{u-a_1}{a_2-a_1} & a_1 & u & a_2 \\ \frac{a_3-u}{a_3-a_2} & a_2 & u & a_3 \\ 0 & otherwise \end{cases}$$

Where w = [1, ...). We denote such a vague number by $\tilde{V} = (a_1, a_2, a_3, w)_T$.

Proposition 1.(Taheri and Zarei (2011); Resolution Identity for Vague Sets) Let $\tilde{V}_{t_{\tilde{V}},f_{\tilde{V}}}$ be a vague set of U. Then

$$t_{\widetilde{V}}(u) = \sup_{\alpha_t [0,1]} \alpha_t . I_{\widetilde{V}_{\alpha_t}}(u), \quad 0 \quad \alpha_t \quad 1,$$

$$f_{\widetilde{V}}(u) = \sup_{\alpha_f [0,1]} \alpha_f . I_{\widetilde{V}_{\alpha_f}}(u), \quad 0 \quad \alpha_f \quad 1,$$

Where, I(.) is denoted for the indicator function.

3. Vague point estimator

With according to Taheri and Zarei (2011), Let $\tilde{X}: \Omega \to V(\mathcal{R})$ be a vague valued function. Then, \tilde{X} is called to be a vague random variable if $\tilde{X}_{\alpha t}^{L} \tilde{X}_{\alpha t}^{U}, \tilde{X}_{\alpha f}^{L}$ and $\tilde{X}_{\alpha f}^{U}$ for all 0 : t_{ℓ} : f 1, are (ordinary) random variables. Too, Let \tilde{X} be a vague random variable whose distribution depends on a vague parameter $\tilde{\theta}$. So, it could be said that $\tilde{\theta}_{\alpha t}^{L} \tilde{\theta}_{\alpha t}^{U}, \tilde{\theta}_{\alpha f}^{L}$ and $\tilde{\theta}_{\alpha f}^{U}$ are the parameters of distributions of (crisp) random variables $\tilde{X}_{\alpha t}^{L} \tilde{X}_{\alpha t}^{U}, \tilde{X}_{\alpha f}^{L}$ and $\tilde{X}_{\alpha f}^{U}$, respectively. Our purpose is to estimate $\tilde{\theta}$ based on a Bayes approach. According to this approach, $\tilde{\theta}$ is considered as a vague random variable so that the crisp random variables $\tilde{\theta}_{\alpha t}^{L} \tilde{\theta}_{\alpha t}^{U}, \tilde{\theta}_{\alpha f}^{L}$ and $\tilde{\theta}_{\alpha f}^{U}$ have some distributions with parameters $(\tilde{\eta}_{1})_{\alpha t'}^{L}, \dots, (\tilde{\eta}_{m})_{\alpha t'}^{L}, (\tilde{\chi}_{1})_{\alpha f}^{U}, \dots, (\tilde{\zeta}_{m})_{\alpha f}^{L}, (\tilde{\zeta}_{1})_{\alpha f}^{U}, \dots, (\tilde{\zeta}_{m})_{\alpha f}^{U}$

Concerning Definition 7, we can find the Bayes point estimator $\hat{\theta}$ for each $\theta = \begin{bmatrix} \tilde{\theta}_{\alpha_{t'}}^L \tilde{\theta}_{\alpha_t}^U \end{bmatrix}$. Consider

$$V_{\alpha_{t}} = \left| \min\{ \inf_{\alpha_{t} \le \beta_{t} \le 1} \widehat{\widehat{\theta}_{\beta_{t}'}^{L}}, \inf_{\alpha_{t} \le \beta_{t} \le 1} \widehat{\widehat{\theta}_{\beta_{t}}^{U}} \}, \max\{ \sup_{\alpha_{t} \le \beta_{t} \le 1} \widehat{\widehat{\theta}_{\beta_{t}'}^{L}}, \sup_{\alpha_{t} \le \beta_{t} \le 1} \widehat{\widehat{\theta}_{\beta_{t}}^{U}} \} \right|$$
(1)

Then, V_{α_t} contains all of the Bayes point estimators for each $\theta = \begin{bmatrix} \tilde{\theta}_{\alpha_{t'}}^L \tilde{\theta}_{\alpha_t}^U \end{bmatrix}$. The same argument can be established for $\theta = \begin{bmatrix} \tilde{\theta}_{\alpha_{f'}}^L \tilde{\theta}_{\alpha_f}^U \end{bmatrix}$.

The vague Bayes point estimator for the vague parameter $\tilde{\theta}$ is defined to be a vague number $\hat{\theta}_{t_{\overline{v}},f_{\overline{v}}}$, where

$$t_{\widehat{\theta}}(u) = \sup_{\alpha \in [0,1]} \alpha_t I_{\widehat{\theta}_{\alpha_t}}(u), \quad 0 \quad \alpha_t = 1, \quad (2)$$

$$f_{\widehat{\theta}}(u) = \sup_{\alpha_f [0,1]}^{\alpha_f [0,1]} \alpha_f I_{\widehat{\theta}_{\alpha_f}}(u), \quad 0 \quad \alpha_f = 1, \quad (3)$$

4. Vague Bayesian system reliability and availability

In the Bayesian approach to system reliability, some prior distributions are assigned to the components of the system. Then, the posterior distribution of each component's reliability can be found using the Bayes theorem. We can derive, therefore, the posterior distribution of the system reliability from the posterior distribution of each component reliability. The key point in this approach is that system reliability can be expressed as a product of independentrandom variables which corresponds to either component reliability (for series system) or to component unreliability (for parallel systems). To this end, we need to use the method of Mellin integral transform [2] described below.

4.1 Mellin transformation

Definition 9. [2] Let X be a non-negative random variable with pdf f(x). The Mellin transform of f, with respect to the complex parameter, is defined by

$$M(f; u) = \int_0^\infty x^{u-1} f(x) d(x)$$
 (4)

Such a transform exists if $\int_0^\infty x^{u-1} |f(x)| d(x)$ is bounded for some u > 0.

Remark1. Based on the above definition, the inverse Mellin transform of M(f; u) is given by $f(t) = \int_{\sigma-i\infty}^{\sigma+i\infty} x^{-u} M(f, u) du$, where $\sigma - i\infty$ and $\sigma + i$ are complex values [2].

Remark 2. It is convenient to regard the Mellin transform as the moments of X, i.e.

$$M(f; u) = E(X^{u-1}).$$

Theorem 1. [25] Let X_1, \ldots, X_k be independent random variables with pdf's f_1, \ldots, f_k respectively. Let $g_k(y)$ be the pdf of the random variable $Y = \sum_{i=1}^{k} X_i$. Then

$$M(g_k; u) = \prod_{i=1}^{k} M(f_i; u)$$
. (5)

With the help of Theorem1, we can obtain the posterior distribution of the system reliability from the posterior distribution of the component reliabilities. On the other hand, the Bayes estimator of the system reliability, under the squared error loss function, is the mean of the posterior distribution [21], so that we can use Eq. (4), for u = 2, to obtain the Bayes estimator of the system reliability.

4.2 Bayesian approach to system reliability

The fuzzy Bayesian interval estimate of reliability is calculated using the method proposed by Wu (2006). Let random variable T_{ij} be the *j*th failure time of the *i*th components t_{ij} be the realization of this random variable, $j = 1, 2, ..., m_i$, i = 1, 2, ..., k. It is assumed that T_{ij} , $j = 1, 2, ..., m_i$, are independent and identically distributed exponential random variables with parameter λ_i . λ_i is unknown; therefore, a gamma distribution with parameters θ_{i1} and θ_{i2} is assigned as prior distribution to quantify the uncertainty in λ_i . From previous experience we know the parameters of the prior distribution θ_{i1} and θ_{i2} . They can be interpreted as θ_{i1} numbers of failures that occur in the duration θ_{i2} for component isince the expected value of gamma distribution is $\theta_{i1} / \theta_{i2}$. On the total operating time of v_i , $\left(v_i = \prod_{j=1}^{m_i} t_{ij}\right)$, m_i failures are observed for the component *i*. Since the gamma distribution is a conjugate prior distribution for the exponential sampling distribution, the posterior distribution of λ_i is a gamma distribution with parameters $(\theta_{i1} + m_i)$ and $(\theta_{i2} + v_i)$. Reliability of the components i for the duration *t* is $r_i(t) = e^{-\lambda_i t^*}$ and it is monotonically decreasing function of λ_i , so there is aone-to-one relationship between λ_i and r_i . Therefore the unique inverse is $\int_{i}^{i} -\ln r_i / t$ so the distribution of λ_i as

$$f(r_i) = g\left(\frac{-\ln r_i}{t^*}\right) \left|\frac{\mathrm{d}\lambda_i}{\mathrm{d}r_i}\right| = g\left(\frac{-\ln r_i}{t^*}\right) \left(\frac{1}{r_i t^*}\right),$$

Where $f(r_i)$ is either prior or posterior distribution of r_i and $g(\lambda_i)$ is corresponding prior or posterior distribution of λ_i (Martz and Waller, 1991). Assigning a gamma (θ_{i1}, θ_{i2}) prior distribution to r_i corresponds to assigning a Negative-Log-Gamma (θ_{i1}, θ_{i2} /t) prior distribution

to r_i . Given the data, the posterior distribution of r_i is a Negative-Log-Gamma $(m_i + \theta_{i1}, (\nu_i + \theta_{i2})/t)$ distribution.

Series system

Consider a series system consisting of k independent components. The system reliability is $R = \sum_{i=1}^{k} R_i$. So from Eq. (5), the Mellin transform of the $\pi(r|m_i, \nu_i)$ of system reliability is given by

$$M[\pi_R(r|m_i, v_i); u] = \frac{k}{i=1} \left(\frac{v_i + \theta_{i2}}{v_i + \theta_{i2} + (u-1)t_i} \right)^{m_i + \theta_{i1} + 1}$$
(6)

Under a squared error loss function, the Bayes point estimate of the system reliability r isgiven as $\hat{r}_s = E[R|m, \nu] = M[\pi_R(r|m_i, \nu_i); u = 2] = \frac{k}{k!=1} \left(\frac{\nu_i + \theta_{i2}}{\nu_i + \theta_{i2} + t}\right)^{m_i + \theta_{i1}}$ (7)

The Bayes point estimate of the system reliability *r* under a precautionary loss function is:

$$\hat{r_p} = (E[R^2|m,\nu])^{\frac{1}{2}} = (M[\pi_R(r|m_i,\nu_i);u=3])^{\frac{1}{2}} = \frac{k}{i=1} \left(\frac{\nu_i + \theta_{i2}}{\nu_i + \theta_{i2} + 2t}\right)^{\frac{m_i + \theta_{i1}}{2}} (8)$$

Now, suppose in a complex system the number of failures and failure times may be recorded imprecisely due to equipment and human errors. For such cases this imprecision also should be quantified in the calculations. Here vague set theory is used to quantify the uncertainty of imprecision. Failure rate, __i, reliability, r_i, and failure times, t_{ij}, are taken as vague random variables. It is assumed that prior distribution parameters are known from the previous experience so those θ_{i1} and θ_{i2} are taken as vague number (the parameter __{i1} can be interpreted as the 'pseudo' number of and failures in a lifetime test of duration 'i2 'pseudo' time units).the Bayes point estimates of $(\tilde{r}_s)^L_{\alpha_t}$, $(\tilde{r}_s)^U_{\alpha_t}$ and $(\tilde{r}_s)^U_{\alpha_f}$ under a squared error loss function are given by

$$\begin{aligned} \left(\widehat{r}_{s}^{*}\right)_{\alpha_{t}}^{L} &= \prod_{i=1}^{k} \left(\frac{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{L}} &= \left[\lim_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{U}}}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \\ \left(\widehat{r}_{s}^{*}\right)_{\alpha_{t}}^{U} &= \prod_{i=1}^{k} \left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{L}}}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} &= \lim_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(\widetilde{r}_{s})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}}}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{L}} \\ \left(\widehat{r}_{s}^{*}\right)_{\alpha_{f}}^{L} &= \prod_{i=1}^{k} \left(\frac{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L}}{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}}\right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{L}} \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{U}}}{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \\ &= \prod_{i=1}^{k} \left(\frac{\sum_{i=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}}}{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \\ &= \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \\ &= \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \\ &= \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}{\sum_{j=1}^{m_{i}} (\widetilde{t}_{(ij)})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \right)^{m_{i} + (\theta_{i1})_{\alpha_{f}}^{U}} \\ &= \prod$$

the Bayes point estimates of $(\tilde{r}_p)_{\alpha_t}^L$, $(\tilde{r}_p)_{\alpha_t}^U$, $(\tilde{r}_p)_{\alpha_f}^L$ and $(\tilde{r}_p)_{\alpha_f}^U$ under a precautionary loss function are given by

$$\left(\hat{r}_{p}^{\infty} \right)_{a_{t}}^{L} = \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\hat{t}_{(ij)})_{a_{t}}^{L} + (\theta_{i2})_{\underline{a}_{t}}^{L}}{\sum_{j=1}^{m_{i}} (\hat{t}_{(ij)})_{a_{t}}^{L} + (\theta_{i2})_{\underline{a}_{t}}^{L} + 2t}} \right)^{\frac{m_{i} + (\theta_{i1})_{a_{t}}^{L}}{2}}, \\ \left(\hat{r}_{p}^{\infty} \right)_{a_{f}}^{U} = \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\hat{t}_{(ij)})_{a_{t}}^{L} + (\theta_{i2})_{\underline{a}_{t}}^{L} + \theta_{i2})_{\underline{a}_{t}}^{L}}{2}, \\ \left(\hat{r}_{p}^{\infty} \right)_{a_{f}}^{U} = \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\hat{t}_{(ij)})_{a_{f}}^{L} + (\theta_{i2})_{\underline{a}_{f}}^{L} + (\theta_{i2})_{\underline{a}_{f}}^{L}}{2}, \\ \left(\hat{r}_{p}^{\infty} \right)_{a_{f}}^{U} = \prod_{i=1}^{k} \left(\frac{\sum_{j=1}^{m_{i}} (\hat{t}_{(ij)})_{a_{f}}^{L} + (\theta_{i2})_{\underline{a}_{f}}^{L} + (\theta_{i2})_{\underline{a}_{f}}^{L} + \theta_{i2})_{a_{f}}^{L} + \theta_{i2})_{a_{f}}^{U} + \theta_{i2})_{a_{f}}^{U} + \theta_{i2})_{a_{f}}^{U} + \theta_{i2})_{a_{f}}^{U} \right)$$
(11)

Respectively, for all $\alpha \in [0,1]$. According to the discussions in Section 3, let

$$V_{\alpha_{t}} = \left| \min\{\inf_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{t}}^{L}}, \inf_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\theta_{\beta_{t}}^{U}} \}, \max\{\sup_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\theta_{\beta_{t}}^{L}}, \sup_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\theta_{\beta_{t}}^{U}} \} \right|$$

The above intervals contain all of the Bayes estimators for each r $[\tilde{r}_{\alpha_t}^L, \tilde{r}_{\alpha_t}^U]$. The same intervals can be established for $r = \left[\tilde{r}_{\alpha_f}^L, \tilde{r}_{\alpha_f}^U \right]$. But, for $< \beta$ have

> $\widehat{r}^{L}_{\alpha} \quad \widehat{r}^{U}_{\alpha}, \quad \widehat{r}^{L}_{\alpha} \quad \widehat{r}^{U}_{\beta}, \quad \widehat{r}^{U}_{\beta}, \quad \widehat{r}^{U}_{\alpha} \quad \widehat{r}^{U}_{\beta},$ $\widehat{ ilde{r}_{lpha}^{L}} = \widehat{ ilde{r}_{1}^{U}} = \widehat{ ilde{r}_{1}^{U}} = \widehat{ ilde{r}_{1}^{U}} = \widehat{ ilde{r}_{lpha}^{U}}.$

And so

Therefore, V_{α_t} and V_{α_f} can be rewritten as

$$V_{\alpha_t} = \left[\widehat{\tilde{r}_{\alpha_t}^L}, \widehat{\tilde{r}_{\alpha_t}^U}\right](13)$$
$$V_{\alpha_f} = \left[\widehat{\tilde{r}_{\alpha_f}^L}, \widehat{\tilde{r}_{\alpha_f}^U}\right](14)$$

Now, using Proposition 1, the truth membership function and the false membership function of the vague Bayes estimate of \tilde{r} , denoted by $\hat{\tilde{r}}$, are defined as follows

$$t_{\hat{r}}(r) = \sup_{\alpha_t \in [0,1]} \alpha_t . I_{\hat{r}_{\alpha_t}}(r), \quad 0 \quad \alpha_t \quad 1$$
(15)
$$f_{\hat{r}}(r) = \sup_{\alpha_f \in [0,1]} \alpha_f . I_{\hat{r}_{\alpha_f}}(r), \quad 0 \quad \alpha_f \quad 1$$
(16)

Parallel systems

For a parallel system consisting of k independent components, the system reliability is R = 1 - 1 $k_{i=1}^{k}(1-r_i)$ where r_i is the component reliability of the *i*th component. Equivalently, the ystemunreliability q is the product of component unreliabilities $q_i = 1 - r_i$, i.e., $q = 1 - r_i$ $_{i=1}^{k} q_i$. The Bayes point estimate of system unreliability is given by 0

$$E[Q|m, \nu] = \prod_{i=1}^{n} E[Q_i|m_i, \nu_i] = \prod_{i=1}^{n} \left[1 - \left(\frac{\nu_i + \theta_{i2}}{\nu_i + \theta_{i2} + t}\right)^{m_i + \theta_{i1}} \right]$$

ad
$$E[Q^2|m,] = \prod_{i=1}^{k} E[Q_i^2|m_i, \nu_i] = \prod_{i=1}^{k} \left[1 - 2\left(\frac{\nu_i + \theta_{i2}}{\nu_i + \theta_{i2} + t}\right)^{m_i + \theta_{i1}} + \left(\frac{\nu_i + \theta_{i2}}{\nu_i + \theta_{i2} + t}\right)^{m_i + \theta_{i1}} \right]$$

And

$$] = \prod_{i=1}^{K} E[Q_i^2 | m_{i, -i_1}] = \prod_{i=1}^{K} \left[1 - 2\left(\frac{\nu_i + \theta_{i_2}}{\nu_i + \theta_{i_2} + t}\right)^{m_i + \theta_{i_1}} + \left(\frac{\nu_i + \theta_{i_2}}{\nu_i + \theta_{i_2} + 2t}\right)^{m_i + \theta_{i_1}}\right]$$

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The Bayes point estimate of the system reliability r under a squared error loss function is given by

$$\widehat{r}_{s} = E[R|m,\nu] = E[(1-Q)|m,\nu] = 1 - E[Q|m,\nu] = 1 - \frac{k}{i=1} \left[1 - \left(\frac{\nu_{i}+\theta_{i2}}{\nu_{i}+\theta_{i2}+t}\right)^{m_{i}+\theta_{i1}} \right]$$
(17)

The Bayes point estimate of the system reliability r under a precautionary loss function is given by

$$\hat{r_p} = (E[R^2|m,v])^{\frac{1}{2}} = (E[(1-Q)^2|m,v])^{\frac{1}{2}} = (E[1-2Q+Q^2|m,v])^{\frac{1}{2}} = \left(1-2\prod_{i=1}^{k} \left[1-\left(\frac{v_i+\theta_{i2}}{v_i+\theta_{i2}+t}\right)^{m_i+\theta_{i1}}\right] + \prod_{i=1}^{k} \left[1-2\left(\frac{v_i+\theta_{i2}}{v_i+\theta_{i2}+t}\right)^{m_i+\theta_{i1}} + \left(\frac{v_i+\theta_{i2}}{v_i+\theta_{i2}+2t}\right)^{m_i+\theta_{i1}}\right]^{\frac{1}{2}}$$
(18)

Under the vague assumptions as described above, the Bayes point estimates $\inf_{\alpha_t} (\tilde{r}_s)_{\alpha_t}^L , (\tilde{r}_s)_{\alpha_t}^U , (\tilde{r}_s)_{\alpha_t}^U$, $(\tilde{r}_s)_{\alpha_t}^L$ and $(\tilde{r}_s)_{\alpha_t}^U$ under a squared error loss function are given by

$$\left(\hat{\tilde{r}_{g}} \right)_{\alpha_{t}}^{L} = 1 - \prod_{i=1}^{k} \left[1 - \left(\frac{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}} \right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{L}} \right], \\ \left(\hat{\tilde{r}_{g}} \right)_{\alpha_{t}}^{U} = 1 - \prod_{i=1}^{k} \left[1 - \left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{L}} \right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \right], \\ \left(\hat{\tilde{r}_{g}} \right)_{\alpha_{f}}^{L} = 1 - \prod_{i=1}^{k} \left[1 - \left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}} \right)^{m_{i} + (\theta_{i2})_{\alpha_{t}}^{U}} \right], \\ \left(\hat{\tilde{r}_{g}} \right)_{\alpha_{f}}^{L} = 1 - \prod_{i=1}^{k} \left[1 - \left(\frac{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}}{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}} \right)^{m_{i} + (\theta_{i2})_{\alpha_{f}}^{U}} \right]$$
(19)

Under the vague assumptions as described above, the Bayes point estimates of $(\tilde{r}_p)_{\alpha_t}^L$, $(\tilde{r}_p)_{\alpha_t}^U$, $(\tilde{r}_p)_{\alpha_f}^U$ and $(\tilde{r}_p)_{\alpha_f}^U$ under a precautionary loss function are given by

$$\begin{aligned} \left(\widehat{r_{p}}\right)_{\alpha_{t}}^{L} &= \left(1 - 2\prod_{i=1}^{k} \left|1 - \left(\frac{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{L}}\right| \\ &+ \prod_{i=1}^{k} \left|1 \\ &- 2\left(\frac{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{L}} \left(\frac{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{L}} \left(\frac{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{U} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \right| \end{aligned}$$

$$\begin{aligned} &+ \prod_{i=1}^{k} \left|1 - 2\left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U} + 2t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \right| \\ \\ &+ \prod_{i=1}^{k} \left|1 - 2\left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U} + t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \left(\frac{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U}}{(v_{i})_{\alpha_{t}}^{U} + (\theta_{i2})_{\alpha_{t}}^{U} + 2t}\right)^{m_{i} + (\theta_{i1})_{\alpha_{t}}^{U}} \right| \end{aligned}$$

$$\begin{split} \left(\hat{\hat{r}_{p}}\right)_{\alpha_{f}}^{L} &= \left(1 - 2\prod_{i=1}^{k} \left[1 - \left(\frac{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L}}{(v_{i})_{\alpha_{t}}^{L} + (\theta_{i2})_{\alpha_{t}}^{L} + t}\right)^{m_{t} + (\theta_{t_{1}})_{\alpha_{f}}^{L}}\right] \\ &+ \prod_{i=1}^{k} \left[1 - 2\left(\frac{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L}}{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L} + t}\right)^{m_{t} + (\theta_{t_{1}})_{\alpha_{f}}^{L}} + \left(\frac{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L}}{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{L}}\right)^{m_{t} + (\theta_{t_{1}})_{\alpha_{f}}^{L}} \\ &\left(\hat{\hat{r}_{p}}\right)_{\alpha_{f}}^{U} = \left(1 - 2\prod_{i=1}^{k} \left[1 - \left(\frac{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}}{(v_{i})_{\alpha_{f}}^{L} + (\theta_{i2})_{\alpha_{f}}^{U} + t}\right)^{m_{t} + (\theta_{i2})_{\alpha_{f}}^{U}}\right] \\ &+ \prod_{i=1}^{k} \left[1 - 2\left(\frac{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}}{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}\right)^{m_{t} + (\theta_{i2})_{\alpha_{f}}^{U}} + \left(\frac{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U}}{(v_{i})_{\alpha_{f}}^{U} + (\theta_{i2})_{\alpha_{f}}^{U} + t}\right)^{m_{t} + (\theta_{i2})_{\alpha_{f}}^{U}}}\right]$$

$$(22)$$

Respectively, for all [0,1] the membership function of the vague Bayes point estimate of system reliability r is defined by the same way as discussed above.

k-out-of-m system

For a k-out-of-m system consisting of m independent and identical components, the system reliability is given by

$$r = \sum_{i=1}^{m} {m \choose j} \bar{r}^{j} (1-\bar{r})^{m-j}$$

That \bar{r} is the reliability of the (common) component. The Bayes point estimate of system reliability r is the mean E[R|s, v] under the squared error loss function, and is given by

$$\widehat{r}_{s} = E[R|s,\nu] = \sum_{j=k}^{m} {m \choose j} \int_{0}^{1} \overline{r}^{j} (1-\overline{r})^{m-j} . \pi(\overline{r}|s,\nu)$$
$$= \lim_{j=k}^{m} \lim_{l=0}^{m-j} (-1)^{l} {m \choose j} {m-j \choose k} \left(\frac{\nu+\theta_{2}}{tl+tj+\nu+\theta_{2}}\right)^{s+\theta_{1}} (23)$$

The Bayes point estimate of system reliability r at time t, under a squared loss function, given by

$$\widehat{r_p} = \left(E[R^2|s,\nu] \right)^{\frac{1}{2}} = \left[\sum_{j=k}^{m} \frac{m}{|i=k|} \frac{2m-(i+j)}{|i=0|} (-1)^l \binom{m}{j} \binom{m-j}{k} \binom{2m-(i+j)}{l} \left(\frac{\nu+\theta_2}{l+l+l+\nu+\theta_2} \right)^{s+\theta_1} \right]^{\frac{1}{2}}$$
(24)

Under the vague assumptions as described above, the Bayes point estimates of $(\tilde{r}_s)^L_{\alpha_t}$, $(\tilde{r}_s)^U_{\alpha_t}$, $(\tilde{r}_s)^L_{\alpha_f}$ and $(\tilde{r}_s)^U_{\alpha_f}$ under a squared error loss function are given by

$$(\hat{\tilde{r}}_{s})_{\alpha_{t}}^{L} = \sum_{j=k}^{m} \sum_{l=0}^{m-j} (-1)^{l} {m \choose j} {m-j \choose k} \left(\frac{\nu_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}}{tl+tj+\nu_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}} \right)^{s+(\theta_{1})_{\alpha_{t}}^{L}}$$

$$(\hat{\tilde{r}}_{s})_{\alpha_{t}}^{U} = \sum_{j=k}^{m} \sum_{l=0}^{m-j} (-1)^{l} {m \choose j} {m-j \choose k} \left(\frac{\nu_{\alpha_{t}}^{U} + (\theta_{2})_{\alpha_{t}}^{U}}{tl+tj+\nu_{\alpha_{t}}^{U} + (\theta_{2})_{\alpha_{t}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{t}}^{U}}$$

$$(\hat{\tilde{r}}_{s})_{\alpha_{f}}^{L} = \sum_{j=k}^{m} \sum_{l=0}^{m-j} (-1)^{l} {m \choose j} {m-j \choose k} \left(\frac{\nu_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{U}}{tl+tj+\nu_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{L}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{L}}$$

$$(\hat{\tilde{r}}_{s})_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \sum_{l=0}^{m-j} (-1)^{l} {m \choose j} {m-j \choose k} \left(\frac{\nu_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{U}}{tl+tj+\nu_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}}$$

$$(25)$$

Under the vague assumptions as described above, the Bayes point estimates of $(\tilde{r}_p)_{\alpha_t}^L$, $(\tilde{r}_p)_{\alpha_t}^U$, $(\tilde{r}_p)_{\alpha_f}^L$ and $(\tilde{r}_p)_{\alpha_f}^U$ under a precautionary loss function are given by

$$\begin{aligned} \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{t}}^{L} &= \sum_{j=k}^{m} \sum_{i=k}^{m} \sum_{l=0}^{m} \sum_{l=0}^{m} \sum_{l=0}^{m-(i+j)} (-1)^{l} {m \choose j} {m-j \choose k} {2m-(i+j) \choose l} \left(\frac{v_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}}{tl+tj+tl+v_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}} \right)^{s+(\theta_{1})_{\alpha_{t}}^{L}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{t}}^{U} &= \sum_{j=k}^{m} \sum_{i=k}^{m} \sum_{l=0}^{m-(i+j)} (-1)^{l} {m \choose j} {m-j \choose k} {2m-(i+j) \choose l} \left(\frac{v_{\alpha_{t}}^{U} + (\theta_{2})_{\alpha_{t}}^{U}}{tl+tj+tl+v_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{t}}^{U}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{t}}^{L} &= \sum_{j=k}^{m} \sum_{i=k}^{m} \sum_{l=0}^{2m-(i+j)} (-1)^{l} {m \choose j} {m-j \choose k} {2m-(i+j) \choose l} \left(\frac{v_{\alpha_{t}}^{U} + (\theta_{2})_{\alpha_{t}}^{L}}{tl+tj+tl+v_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}} \right)^{s+(\theta_{1})_{\alpha_{t}}^{L}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{j=k}^{m} \sum_{i=k}^{m} \sum_{l=0}^{2m-(i+j)} (-1)^{l} {m \choose j} {m-j \choose k} {2m-(i+j) \choose l} \left(\frac{v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{L}}{tl+tj+tl+v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{L}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{i=k}^{m} \sum_{l=0}^{m} \sum_{l=0}^{2m-(i+j)} (-1)^{l} {m \choose j} {m-j \choose k} \left(2m-(i+j) \choose l} \left(\frac{v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}}{tl+tj+tl+v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{i=k}^{m} \sum_{l=0}^{2m-(i+j)} (-1)^{l} {m \choose j} {m-j \choose k} \left(2m-(i+j) \choose l} \right) \left(\frac{v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}}{tl+tj+tl+v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{i=k}^{2m} \sum_{l=0}^{2m-(i+j)} (-1)^{l} {m \choose j} \left(2m-(i+j) \choose l} \right) \left(\frac{v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}}{tl+tj+tl+v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{l=0}^{2m-(i+j)} \left(\frac{v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}}{tl+tj+tl+v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}} \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{l=0}^{2m} \sum_{l=0}^{2m-(i+j)} \left(\frac{v_{\alpha_{f}}^{U} + (\theta_{1})_{\alpha_{f}}^{U}}{tl+tj+tl+v_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}} \right)^{s+(\theta_{1})_{\alpha_{f}}^{U}} \\ \\ \left(\widehat{r}_{p}^{\circ}\right)_{\alpha_{f}}^{U} &= \sum_{l=0}^{2m} \sum_{l=0}$$

Respectively, for all [0,1] the membership function of the vague Bayes point estimate of system reliability r is defined by the same way as discussed above.

4.3 Bayesian approach to system availability

Martz and Waller, (1991) presented the method to calculate the availability of a repairable system

$$A = \frac{E(X)}{E(X) + E(Y)} = \frac{\mu}{\mu + \lambda}$$
(29)

That X is the failure time and Y is the repair time. Assume X and Y are independent variables and have exponential distributions with parameters and μ respectively. Separate gamma distributions are assigned as prior distributions to and μ . To determine the availability of the system, the parameters of exponential distribution should be estimated. Vague Bayesian estimations under the squared error loss function by use Wu (2004) are given by

$$\left(\hat{\lambda}_{s}\right)_{\alpha_{t}}^{L} = \frac{s + (\theta_{1})_{\alpha_{t}}^{L}}{(t)_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}}, \qquad \left(\hat{\lambda}_{s}\right)_{\alpha_{t}}^{U} = \frac{s + (\theta_{1})_{\alpha_{t}}^{U}}{(t)_{\alpha_{t}}^{U} + (\theta_{2})_{\alpha_{t}}^{U}}$$
(30)

$$\left(\hat{\tilde{\lambda}}_{s}\right)_{\alpha_{f}}^{L} = \frac{s + (\theta_{1})_{\alpha_{f}}^{L}}{(t)_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{L}}, \qquad \left(\hat{\tilde{\lambda}}_{s}\right)_{\alpha_{f}}^{U} = \frac{s + (\theta_{1})_{\alpha_{f}}^{U}}{(t)_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}}$$
(31)

Vague Bayesian estimations under the precautionary loss function are given by

$$\left(\hat{\lambda}_{p}\right)_{\alpha_{t}}^{L} = \left[\frac{\left(s + (\theta_{1})_{\alpha_{t}}^{L}\right)\left(s + (\theta_{1})_{\alpha_{t}}^{L} + 1\right)}{\left((t)_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}\right)^{2}}\right]^{\frac{1}{2}}, \quad \left(\hat{\lambda}_{p}\right)_{\alpha_{t}}^{U} = \left[\frac{\left(s + (\theta_{1})_{\alpha_{t}}^{U}\right)\left(s + (\theta_{1})_{\alpha_{t}}^{U} + 1\right)}{\left((t)_{\alpha_{t}}^{U} + (\theta_{2})_{\alpha_{t}}^{U}\right)^{2}}\right]^{\frac{1}{2}}$$
(32)

$$\left(\hat{\lambda}_{p}\right)_{\alpha_{f}}^{L} = \left[\frac{\left(s + (\theta_{1})_{\alpha_{f}}^{L}\right)\left(s + (\theta_{1})_{\alpha_{f}}^{L} + 1\right)}{\left((t)_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{L}\right)^{2}}\right]^{\frac{1}{2}}, \quad \left(\hat{\lambda}_{p}\right)_{\alpha_{f}}^{U} = \left[\frac{\left(s + (\theta_{1})_{\alpha_{f}}^{U}\right)\left(s + (\theta_{1})_{\alpha_{f}}^{U} + 1\right)}{\left((t)_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}\right)^{2}}\right]^{\frac{1}{2}}$$
(33)

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 θ_1 and θ_2 are the prior distribution parameters of λ ; they are assumed to be known from previous experience. For the parameter of repair time distribution, vague Bayes point estimators under the squared error loss function are given in (34) and (35)

$$\left(\hat{\mu}_{s} \right)_{\alpha_{t}}^{L} = \frac{n + (\gamma_{1})_{\alpha_{t}}^{L}}{(t)_{\alpha_{t}}^{L} + (\gamma_{2})_{\alpha_{t}}^{L}}, \qquad \left(\hat{\mu}_{s} \right)_{\alpha_{t}}^{U} = \frac{n + (\gamma_{1})_{\alpha_{t}}^{U}}{(t)_{\alpha_{t}}^{U} + (\gamma_{2})_{\alpha_{t}}^{U}} (34)$$

$$\left(\hat{\mu}_{s} \right)_{\alpha_{f}}^{L} = \frac{n + (\gamma_{1})_{\alpha_{f}}^{L}}{(t)_{\alpha_{f}}^{L} + (\gamma_{2})_{\alpha_{f}}^{L}}, \qquad \left(\hat{\mu}_{s} \right)_{\alpha_{f}}^{U} = \frac{n + (\gamma_{1})_{\alpha_{f}}^{U}}{(t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}} (35)$$

Vague Bayesian estimations under the precautionary loss function are given by

$$\left(\hat{\mu}_{p}\right)_{\alpha_{t}}^{L} = \left[\frac{(n+(\gamma_{1})_{\alpha_{t}}^{L})(n+(\gamma_{1})_{\alpha_{t}}^{L}+1)}{\left((t)_{\alpha_{t}}^{L}+(\gamma_{2})_{\alpha_{t}}^{L}\right)^{2}}\right]^{\frac{1}{2}}, \quad \left(\hat{\mu}_{p}\right)_{\alpha_{t}}^{U} = \left[\frac{(n+(\gamma_{1})_{\alpha_{t}}^{U})(n+(\gamma_{1})_{\alpha_{t}}^{U}+1)}{\left((t)_{\alpha_{t}}^{U}+(\gamma_{2})_{\alpha_{t}}^{U}\right)^{2}}\right]^{\frac{1}{2}}$$
(36)

$$\left(\hat{\mu}_{p}\right)_{\alpha_{f}}^{L} = \left[\frac{\left(n + (\gamma_{1})_{\alpha_{f}}^{L}\right)\left(n + (\gamma_{1})_{\alpha_{f}}^{L} + 1\right)}{\left((t)_{\alpha_{f}}^{L} + (\gamma_{2})_{\alpha_{f}}^{L}\right)^{2}}\right]^{\frac{1}{2}}, \quad \left(\hat{\mu}_{p}\right)_{\alpha_{f}}^{U} = \left[\frac{\left(n + (\gamma_{1})_{\alpha_{f}}^{U}\right)\left(n + (\gamma_{1})_{\alpha_{f}}^{U} + 1\right)}{\left((t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}\right)^{2}}\right]^{\frac{1}{2}}$$
(37)

 γ_1 and γ_2 are the prior distribution parameters of μ ; they are assumed to be known from previous experience.

Vague Bayes point estimators under the squared error loss function of availability interval bounds $(\tilde{A}_s)^L_{\alpha_t}, (\tilde{A}_s)^U_{\alpha_t}, (\tilde{A}_s)^L_{\alpha_f}$ and $(\tilde{A}_s)^U_{\alpha_f}$ are given by

$$\left(\hat{A}_{s}\right)_{\alpha_{t}}^{L} = \frac{\frac{n + (\gamma_{1})_{\alpha_{t}}^{L}}{(t)_{\alpha_{t}}^{L} + (\gamma_{2})_{\alpha_{t}}^{L}}}{\frac{n + (\gamma_{1})_{\alpha_{t}}^{L}}{(t)_{\alpha_{t}}^{L} + (\gamma_{2})_{\alpha_{t}}^{L}} + \frac{s + (\theta_{1})_{\alpha_{t}}^{L}}{(t)_{\alpha_{t}}^{L} + (\theta_{2})_{\alpha_{t}}^{L}}} + \left(\hat{A}_{s}\right)_{\alpha_{t}}^{U} \frac{\frac{n + (\gamma_{1})_{\alpha_{t}}^{U}}{(t)_{\alpha_{t}}^{U} + (\gamma_{2})_{\alpha_{t}}^{U}}}{\frac{n + (\gamma_{1})_{\alpha_{t}}^{U}}{(t)_{\alpha_{t}}^{U} + (\gamma_{2})_{\alpha_{t}}^{U}}} + \frac{s + (\theta_{1})_{\alpha_{t}}^{U}}{(t)_{\alpha_{t}}^{U} + (\gamma_{2})_{\alpha_{t}}^{U}}}$$
(38)

$$\left(\hat{A}_{s}\right)_{\alpha_{f}}^{L} = \frac{\frac{n + (\gamma_{1})_{\alpha_{f}}^{L}}{(t)_{\alpha_{f}}^{L} + (\gamma_{2})_{\alpha_{f}}^{L}}}{\frac{n + (\gamma_{1})_{\alpha_{f}}^{L}}{(t)_{\alpha_{f}}^{L} + (\gamma_{2})_{\alpha_{f}}^{L}}} + \frac{s + (\theta_{1})_{\alpha_{f}}^{L}}{(t)_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{L}}}, \left(\hat{A}_{s}\right)_{\alpha_{f}}^{U} = \frac{\frac{n + (\gamma_{1})_{\alpha_{f}}^{U}}{(t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}}}{\frac{n + (\gamma_{1})_{\alpha_{f}}^{U}}{(t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}}} + \frac{s + (\theta_{1})_{\alpha_{f}}^{U}}{(t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}}}$$
(39)

Vague Bayes point estimators under the precautionary loss function of availability interval bounds $(\tilde{A}_p)_{\alpha_t}^L, (\tilde{A}_p)_{\alpha_t}^U, (\tilde{A}_p)_{\alpha_f}^L$ and $(\tilde{A}_p)_{\alpha_f}^U$ are given by

$$\left(\hat{A}_{p} \right)_{\alpha_{t}}^{L} = \frac{ \left[\frac{(n+(\gamma_{1})_{\alpha_{t}}^{L})(n+(\gamma_{1})_{\alpha_{t}}^{L}+1)}{((t)_{\alpha_{t}}^{L}+(\gamma_{2})_{\alpha_{t}}^{L})^{2}} \right]^{\frac{1}{2}}{\left[\frac{(n+(\gamma_{1})_{\alpha_{t}}^{L})(n+(\gamma_{1})_{\alpha_{t}}^{L}+1)}{((t)_{\alpha_{t}}^{L}+(\gamma_{2})_{\alpha_{t}}^{L})^{2}} \right]^{\frac{1}{2}} + \left[\frac{(s+(\theta_{1})_{\alpha_{t}}^{L})(s+(\theta_{1})_{\alpha_{t}}^{L}+1)}{((t)_{\alpha_{t}}^{L}+(\theta_{2})_{\alpha_{t}}^{L})^{2}} \right]^{\frac{1}{2}}$$

$$\left(\hat{A}_{p} \right)_{\alpha_{t}}^{U} = \frac{ \left[\frac{(n+(\gamma_{1})_{\alpha_{t}}^{U})(n+(\gamma_{1})_{\alpha_{t}}^{U}+1)}{((t)_{\alpha_{t}}^{U}+(\gamma_{2})_{\alpha_{t}}^{U})^{2}} \right]^{\frac{1}{2}}{\left[\frac{(n+(\gamma_{1})_{\alpha_{t}}^{U})(n+(\gamma_{1})_{\alpha_{t}}^{U}+1)}{((t)_{\alpha_{t}}^{U}+(\gamma_{2})_{\alpha_{t}}^{U})^{2}} \right]^{\frac{1}{2}} + \left[\frac{(s+(\theta_{1})_{\alpha_{t}}^{U})(s+(\theta_{1})_{\alpha_{t}}^{U}+1)}{((t)_{\alpha_{t}}^{U}+(\theta_{2})_{\alpha_{t}}^{U})^{2}} \right]^{\frac{1}{2}}$$

$$(40)$$

1

$$\begin{pmatrix} \hat{A}_{p} \end{pmatrix}_{\alpha_{f}}^{L} = \frac{\left[\frac{\left(n + (\gamma_{1})_{\alpha_{f}}^{L}\right)\left(n + (\gamma_{1})_{\alpha_{f}}^{L} + 1\right)}{\left((t)_{\alpha_{f}}^{L} + (\gamma_{2})_{\alpha_{f}}^{L}\right)^{2}}\right]^{\frac{1}{2}}}{\left[\frac{\left(n + (\gamma_{1})_{\alpha_{f}}^{L}\right)\left(n + (\gamma_{1})_{\alpha_{f}}^{L} + 1\right)}{\left((t)_{\alpha_{f}}^{L} + (\gamma_{2})_{\alpha_{f}}^{L}\right)^{2}}\right]^{\frac{1}{2}} + \left[\frac{\left(s + (\theta_{1})_{\alpha_{f}}^{L}\right)\left(s + (\theta_{1})_{\alpha_{f}}^{L} + 1\right)}{\left((t)_{\alpha_{f}}^{L} + (\theta_{2})_{\alpha_{f}}^{L}\right)^{2}}\right]^{\frac{1}{2}}}$$

$$\begin{pmatrix} \hat{A}_{p} \end{pmatrix}_{\alpha_{f}}^{U} = \frac{\left[\frac{\left(n + (\gamma_{1})_{\alpha_{f}}^{U}\right)\left(n + (\gamma_{1})_{\alpha_{f}}^{U} + 1\right)}{\left((t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}\right)^{2}}\right]^{\frac{1}{2}}}{\left[\frac{\left(n + (\gamma_{1})_{\alpha_{f}}^{U}\right)\left(n + (\gamma_{1})_{\alpha_{f}}^{U} + 1\right)}{\left((t)_{\alpha_{f}}^{U} + (\gamma_{2})_{\alpha_{f}}^{U}\right)^{2}}\right]^{\frac{1}{2}}} + \left[\frac{\left(s + (\theta_{1})_{\alpha_{f}}^{U}\right)\left(s + (\theta_{1})_{\alpha_{f}}^{U} + 1\right)}{\left((t)_{\alpha_{f}}^{U} + (\theta_{2})_{\alpha_{f}}^{U}\right)^{2}}\right]^{\frac{1}{2}}}$$

$$(41)$$

The availability of a series system consisting of k independent components can be calculated with Eq. (42) (Martz and Waller, 1991)

$$A = \overset{k}{\underset{i=1}{\overset{i}{\underset{i=1}{\overset{j}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\underset{i=1}{\overset{j}{\underset{i=1}{\underset{i=1}{\overset{j}{\underset{i=1}{\overset{j}{\underset{i=1}{\underset{i=1}{\overset{j}{\underset{i=1}{\underset{i=1}{\overset{j}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\overset{j}{\underset{i=1}{\atopi=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\atopi=1}{\underset{i=1}{\atopi=1}$$

Inserting the vague Bayesian estimates of failure and repair rates into (42), vague Bayesian availability equations of a series system under squared error loss functions are given in (43) and (44) respectively

$$\begin{pmatrix} \hat{A}_{s} \end{pmatrix}_{\alpha_{t}}^{L} = {}^{k}_{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{si})_{\alpha_{t}}^{L}}{(\hat{\mu}_{si})_{\alpha_{t}}^{L} + (\hat{\lambda}_{si})_{\alpha_{t}}^{L}} \end{pmatrix}, \\ \begin{pmatrix} \hat{A}_{s} \end{pmatrix}_{\alpha_{t}}^{U} = {}^{k}_{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{si})_{\alpha_{t}}^{U}}{(\hat{\mu}_{si})_{\alpha_{t}}^{U} + (\hat{\lambda}_{si})_{\alpha_{t}}^{U}} \end{pmatrix}$$
(43)
$$\begin{pmatrix} \hat{A}_{s} \end{pmatrix}_{\alpha_{f}}^{L} = {}^{k}_{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{si})_{\alpha_{t}}^{L}}{(\hat{\mu}_{si})_{\alpha_{f}}^{L} + (\hat{\lambda}_{si})_{\alpha_{f}}^{L}} \end{pmatrix}, \\ \begin{pmatrix} \hat{A}_{s} \end{pmatrix}_{\alpha_{f}}^{U} = {}^{k}_{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{si})_{\alpha_{t}}^{U}}{(\hat{\mu}_{si})_{\alpha_{f}}^{U} + (\hat{\lambda}_{si})_{\alpha_{f}}^{U}} \end{pmatrix}$$
(44)

Vague Bayesian availability equations of a series system under precautionary loss functions are given by

$$\begin{pmatrix} \hat{\hat{A}}_{p} \end{pmatrix}_{\alpha_{t}}^{L} = \frac{k}{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{pi})_{\alpha_{t}}^{L}}{(\hat{\mu}_{pi})_{\alpha_{t}}^{L} + (\hat{\bar{\lambda}}_{pi})_{\alpha_{t}}^{L}} \end{pmatrix}, \\ \begin{pmatrix} \hat{\hat{A}}_{p} \end{pmatrix}_{\alpha_{t}}^{U} = \frac{k}{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{pi})_{\alpha_{t}}^{U}}{(\hat{\mu}_{pi})_{\alpha_{t}}^{U} + (\hat{\bar{\lambda}}_{pi})_{\alpha_{f}}^{U}} \end{pmatrix}$$
(45)
$$\begin{pmatrix} \hat{\hat{A}}_{p} \end{pmatrix}_{\alpha_{f}}^{L} = \frac{k}{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{pi})_{\alpha_{t}}^{U}}{(\hat{\mu}_{pi})_{\alpha_{f}}^{U} + (\hat{\bar{\lambda}}_{pi})_{\alpha_{f}}^{U}} \end{pmatrix}, \\ \begin{pmatrix} \hat{\hat{A}}_{p} \end{pmatrix}_{\alpha_{f}}^{U} = \frac{k}{i=1} \begin{pmatrix} \frac{(\hat{\mu}_{pi})_{\alpha_{f}}^{U}}{(\hat{\mu}_{pi})_{\alpha_{f}}^{U} + (\hat{\bar{\lambda}}_{pi})_{\alpha_{f}}^{U}} \end{pmatrix}$$
(46)

Respectively, for all $\alpha \in [0,1]$. According to the discussions in Section 3, let

$$V_{\alpha_t} = \left| \min\{\inf_{\alpha_t \leq \beta_t \leq 1} \widehat{\hat{\theta}_{\beta_t}^L}, \inf_{\alpha_t \leq \beta_t \leq 1} \widehat{\hat{\theta}_{\beta_t}^U} \}, \max\{\sup_{\alpha_t \leq \beta_t \leq 1} \widehat{\hat{\theta}_{\beta_t}^L}, \sup_{\alpha_t \leq \beta_t \leq 1} \widehat{\hat{\theta}_{\beta_t}^U} \} \right|$$

The above intervals contain all of the Bayes estimators for each $A = [\tilde{A}_{\alpha_t}^L, \tilde{A}_{\alpha_t}^U]$. The same intervals can be established for $A = [\tilde{A}_{\alpha_f}^L, \tilde{A}_{\alpha_f}^U]$. But, for $<\beta$ have

$$\widehat{\tilde{A}}_{\alpha}^{L} \leq \widehat{\tilde{A}}_{\alpha}^{U}, \ \widehat{\tilde{A}}_{\alpha}^{L} \leq \widehat{\tilde{A}}_{\beta}^{U}, \ \widehat{\tilde{A}}_{\alpha}^{U} \geq \widehat{\tilde{A}}_{\beta}^{U},$$

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And so

$$\widehat{\tilde{A}}_{\alpha}^{L} \leq \widehat{\tilde{A}}_{1}^{\widetilde{U}} \leq \widehat{\tilde{A}}_{1}^{\widetilde{U}} \leq \widehat{\tilde{A}}_{\alpha}^{\widetilde{U}}.$$

Therefore, V_{α_t} and V_{α_f} can be rewritten as

$$V_{\alpha_t} = \begin{bmatrix} \tilde{A}_{\alpha_t}^{\widehat{L}}, \tilde{A}_{\alpha_t}^{\widehat{U}} \end{bmatrix}$$

$$V_{\alpha_f} = \begin{bmatrix} \tilde{A}_{\alpha_f}^{\widehat{L}}, \tilde{A}_{\alpha_f}^{\widehat{U}} \end{bmatrix}$$
(47)
(47)

Now, using Proposition 1, the truth membership function and the false membership function of the vague Bayes estimate of \tilde{A} , denoted by \hat{A} , are defined as follows

$$t_{\hat{A}}(A) = \sup_{\alpha_t \in [0,1]} \alpha_t \cdot I_{\hat{A}_{\alpha_t}}(A), \quad 0 \quad \alpha_t \quad 1$$
(49)

$$f_{\hat{A}}(A) = \sup_{\alpha_f \in [0,1]} \alpha_f I_{\hat{A}_{\alpha_f}}(A), \quad 0 \quad \alpha_t \quad 1$$
(50)

The availability of a parallel system consisting of k independent components can be calculated with Eqs. (51)–(53) (Martz and Waller, 1991)

Unavailability of system =
$$\overline{A} = 1 - A$$
 (51)

$$\overline{A} = \prod_{i=1}^{k} \left(\frac{\lambda_i}{\mu_i + \lambda_i}\right)$$
(52)

$$A = 1 - \prod_{i=1}^{k} \left(\frac{\lambda_i}{\mu_i + \lambda_i}\right)$$
(53)

In the same way, inserting the vague Bayesian estimates of failure and repair rate into (50), Vague Bayesian availability equations of a parallel system under squared error loss functions are given in (53) and (54) respectively

$$\left(\hat{A}_{s}\right)_{\alpha_{t}}^{L} = 1 - \frac{k}{i=1} \left(\frac{\left(\hat{\lambda}_{si}\right)_{\alpha_{t}}^{L}}{\left(\hat{\mu}_{si}\right)_{\alpha_{t}}^{L} + \left(\hat{\lambda}_{si}\right)_{\alpha_{t}}^{L}} \right), \quad \left(\hat{A}_{s}\right)_{\alpha_{t}}^{U} = 1 - \frac{k}{i=1} \left(\frac{\left(\hat{\lambda}_{si}\right)_{\alpha_{t}}^{U}}{\left(\hat{\mu}_{si}\right)_{\alpha_{t}}^{U} + \left(\hat{\lambda}_{si}\right)_{\alpha_{t}}^{U}} \right)$$
(54)
$$\left(\hat{A}_{s}\right)_{\alpha_{f}}^{L} = 1 - \frac{k}{i=1} \left(\frac{\left(\hat{\lambda}_{si}\right)_{\alpha_{f}}^{L}}{\left(\hat{\mu}_{si}\right)_{\alpha_{f}}^{L} + \left(\hat{\lambda}_{si}\right)_{\alpha_{f}}^{L}} \right), \quad \left(\hat{A}_{s}\right)_{\alpha_{f}}^{U} = 1 - \frac{k}{i=1} \left(\frac{\left(\hat{\lambda}_{si}\right)_{\alpha_{t}}^{U}}{\left(\hat{\mu}_{si}\right)_{\alpha_{f}}^{U} + \left(\hat{\lambda}_{si}\right)_{\alpha_{f}}^{U}} \right)$$
(55)

Vague Bayesian availability equations of a parallel system under precautionary loss functions are given by

$$\left(\hat{\hat{A}}_{p}\right)_{\alpha_{t}}^{L} = 1 - \frac{k}{i+1} \left(\frac{\left(\hat{\lambda}_{pi}\right)_{\alpha_{t}}^{L}}{\left(\hat{\mu}_{pi}\right)_{\alpha_{t}}^{L} + \left(\hat{\lambda}_{pi}\right)_{\alpha_{t}}^{L}} \right), \left(\hat{\hat{A}}_{p}\right)_{\alpha_{t}}^{U} = 1 - \frac{k}{i+1} \left(\frac{\left(\hat{\lambda}_{pi}\right)_{\alpha_{t}}^{U}}{\left(\hat{\mu}_{pi}\right)_{\alpha_{t}}^{U} + \left(\hat{\lambda}_{pi}\right)_{\alpha_{t}}^{U}} \right)$$
(56)
$$\left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{L} = 1 - \frac{k}{i+1} \left(\frac{\left(\hat{\lambda}_{pi}\right)_{\alpha_{f}}^{L}}{\left(\hat{\mu}_{pi}\right)_{\alpha_{f}}^{L} + \left(\hat{\lambda}_{pi}\right)_{\alpha_{f}}^{L}} \right), \left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{U} = 1 - \frac{k}{i+1} \left(\frac{\left(\hat{\lambda}_{pi}\right)_{\alpha_{f}}^{U}}{\left(\hat{\mu}_{pi}\right)_{\alpha_{f}}^{L} + \left(\hat{\lambda}_{pi}\right)_{\alpha_{f}}^{U}} \right)$$
(57)

Respectively, for all [0,1] the membership function of the vague Bayes point estimate of system availability *A* is defined by the same way as discussed above.

For a k-out-of-m system consisting of m independent and identical components, the system availability is given by

$$A = \prod_{j=k}^{m} A^{j} (1 - A)^{m-j}$$
(58)

$$A = \lim_{j \neq k} \left[\left(\frac{\mu}{\mu + \lambda} \right)^j \left(\frac{\lambda}{\mu + \lambda} \right)^{m-j} \right]$$

Vague Bayesian availability equations of a k-out-of-m system under squared error loss functions is given by

(59)

$$\left(\hat{\hat{A}}_{s}\right)_{\alpha_{t}}^{L} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L}}{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{m-j} \right], \\ \left(\hat{\hat{A}}_{s}\right)_{\alpha_{t}}^{L} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{m-j} \right], \\ \left(\hat{\hat{A}}_{s}\right)_{\alpha_{t}}^{L} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}{\left(\hat{\mu}_{s}\right)_{a_{t}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{m-j} \right], \\ \left(\hat{\hat{A}}_{s}\right)_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\mu}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U}}{\left(\hat{\mu}_{s}\right)_{a_{f}}^{L} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{L}}\right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U}}}{\left(\hat{\mu}_{s}\right)_{a_{f}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{f}}^{U}}\right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U}}}{\left(\hat{\mu}_{s}\right)_{a_{f}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{f}}^{U}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U}}}{\left(\hat{\mu}_{s}\right)_{a_{f}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{f}}^{U}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U}}}{\left(\hat{\mu}_{s}\right)_{a_{f}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{f}}^{U}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U}}\right)^{j}}{\left(\hat{\mu}_{s}\right)_{a_{f}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{f}}^{U}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_{s}\right)_{a_{t}}^{U} + \left(\hat{\lambda}_$$

Vague Bayesian availability equations of a parallel system under precautionary loss functions are given by

$$\left(\hat{\hat{A}}_{p}\right)_{\alpha_{t}}^{L} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}\right)^{j}} \left(\frac{\left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}\right)^{j}} \right)^{j} \left(\frac{\left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}\right)^{m-j}} \right], \left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{U}}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{L}}\right)^{m-j}} \right], \left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{U}}\right)^{m-j}} \right], \left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{U}}}{\left(\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{L} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{U}}\right)^{m-j}} \right)^{m-j} \right], \left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\lambda}}_{v}\right)_{a_{t}}^{U}}\right)^{m-j} \right], \left(\hat{\hat{A}}_{p}\right)_{\alpha_{f}}^{U} = \sum_{j=k}^{m} \left[\left(\frac{\left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^{U} + \left(\hat{\hat{\mu}}_{v}\right)_{a_{t}}^$$

4 Computational procedures and example

we need to apply some computational techniques for evaluating the truth and false membership degrees of the vague Bayes point estimate as presented in Eq. (2) and Eq. (3) will be provided. From Eq. (1), we adopt the following notations

$$V_{\alpha_{t}} = [g(\alpha_{t}), h(\alpha_{t})] = [min\{g_{1}(\alpha_{t}), g_{2}(\alpha_{t})\}, max\{h_{1}(\alpha_{t}), h_{2}(\alpha_{t})\}]$$
(64)
$$V_{\alpha_{f}} = [g(\alpha_{f}), h(\alpha_{f})] = [min\{g_{1}(\alpha_{f}), g_{2}(\alpha_{f})\}, max\{h_{1}(\alpha_{f}), h_{2}(\alpha_{f})\}]$$
(65)

Where

$$g_{1}(\alpha_{t}) = \inf_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{t}'}^{L}} \quad g_{2}(\alpha_{t}) = \inf_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{t}'}^{U}} \quad h_{1}(\alpha_{t}) = \sup_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{t}}^{L}} \quad h_{2}(\alpha_{t}) = \sup_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{t}}^{U}},$$
$$g_{1}(\alpha_{f}) = \inf_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{f}}^{L}}, \quad g_{2}(\alpha_{f}) = \inf_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{f}}^{U}}, \quad h_{1}(\alpha_{f}) = \sup_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{f}'}^{L}} \quad h_{2}(\alpha_{f}) = \sup_{\alpha_{t} \leq \beta_{t} \leq 1} \widehat{\widehat{\theta}_{\beta_{f}'}^{U}},$$

From Eq. (1), the truth and false membership functions of the vague Bayes estimate $\hat{\hat{\theta}}$, are given by

$$t_{\widehat{\theta}}(r) = \sup_{\alpha_t \in [0,1]} \alpha_t I_{V_{\alpha_t}}(r) = \sup\{\alpha_t : g(\alpha_t) \quad r \quad h(\alpha_t), \quad 0 \quad \alpha_t = 1\},$$
(66)

$$f_{\widehat{\theta}}(r) = \sup_{\alpha_f [0,1]} \alpha_f \cdot I_{V_{\alpha_f}}(r) = \sup\{\alpha_f \colon g(\alpha_f) \le r \le h(\alpha_f), \quad 0 \le \alpha_f \quad 1\}.$$
(67)

Therefore, needs to be solved the following type of nonlinear programming problem

 $\max \alpha_f$ $\max \alpha_t$ subject to min $\{g_1(\alpha_f), g_2(\alpha_f)\} \le r$ subject to min{ $g_1(\alpha_t), g_2(\alpha_t)$ } r $\max\{h_1(\alpha_t), h_2(\alpha_t)\} = r$ $\max\{h_1(\alpha_f), h_2(\alpha_f)\} \ge r$ $0 \le \alpha_t \le 1$ 0 α_t Now, the following eight sub-problems have been considered $I_F:\max \alpha_f$ $I_T: \max \alpha_t$ subject to $g_1(\alpha_t) \leq r$ subject to $g_1(\alpha_f) \leq r$ $h_1(\alpha_t) \ge r$ $h_1(\alpha_f) \ge r$ $0 \le \alpha_t \le 1$ $0 \le \alpha_t \le 1$ $II_F: \max \alpha_f$ $II_{\tau}:\max \alpha_{t}$ subject to $g_1(\alpha_f) \leq r$ subject to $g_1(\alpha_t) \leq r$ $h_2(\alpha_t) \ge r$ $h_2(\alpha_f) \ge r$ $0 \le \alpha_t \le 1$ $0 \le \alpha_t \le 1$ $III_F:\max \alpha_f$ III_T : max α_t subject to $g_2(\alpha_t) \leq r$ subject to $g_2(\alpha_f) \leq r$ $h_1(\alpha_t) \ge r$ $h_1(\alpha_f) \ge r$ $0 \le \alpha_t \le 1$ $0 \le \alpha_t \le 1$ $IV_F: \max \alpha_f$ $IV_{\tau}: \max \alpha_{\tau}$ subject to $g_2(\alpha_f) \leq r$ subject to $g_2(\alpha_t) \leq r$ $h_2(\alpha_f) \ge r$ $0 \le \alpha_t \le 1$ $h_2(\alpha_t) \ge r$ $0 \le \alpha_t \le 1$

Let and $Z_{IV_T}^*$ be the objective values of subproblems $I_T - IV_T$, and $Z_{I_F}^*, Z_{II_F}^*, Z_{II_F}^*$ and $Z_{IV_F}^*$ be the objective values of subproblems $I_F - IV_F$, respectively. Assume that,

 $Z_T^* = max\{Z_{I_T}^*, Z_{II_T}^*, Z_{IV_T}^*\}$ and $Z_F^* = max\{Z_{I_F}^*, Z_{II_F}^*, Z_{IV_F}^*\}$. Let Z_{0T}^* and Z_{0F}^* be the objective values of the original problems with optimal solution α_t^{*0} and α_f^{*0} respectively (in fact $\alpha_t^{*0} = Z_{0T}^*, \alpha_f^{*0} = Z_{0F}^*$). In according to Wu (2004), we have $Z_t^* = Z_{0T}^*$ and $Z_f^* = Z_{0F}^*$, so to obtain the objective value Z_{0T}^* and Z_{0F}^* of the original nonlinear programming problems, it will be enough to just solve the eight sub-problems $I_T - IV_T$ and $I_F - IV_F$.

Example 5.1. We consider a series-parallel system consisting of three independent components that have Exponential distributions, that structure as shown in Fig. 1.

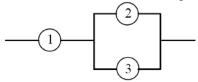


Fig. 2. The series–parallel system

The follow data show that the failure times and repair times are assumed as vague numbers, since the failure times and repair times cannot be recorded precisely due to human errors, machine errors, or some unexpected situations. The simulated failure times and repair times are presented in Table 1. For example component 1, the first failure time and repair time are around 20 and 15 h, respectively.the second failure time and repair time are around30 and 20h. There are the same explanations for components 2 and 3. The prior distribution parameters (pseudo) of the failure rate and repair rate are presented in Table 2.

	-			
	Component 1	Component 2	Component 3	
Failure times				
1	$\widetilde{20}$	50	45	
2	30	35	35	
Repair times	ĩ 5	25	$\widetilde{20}$	
1	15	25	20	
2	20	<u>10</u>	15	
Table 2: Prior distribut	-			
	Component 1	Component?	Component 3	
Failure rate parameters (θ_{i1}, θ_{i2}	(õ, 140)	(5,120)	(8, 180)	
Repair rate parameters(γ_{i1}, γ_{i2})	(3,55)	(4 ,70)	(ŝ,85)	

International Journal on Soft Computing (IJSC) Vol.3, No.1, February 2012 Iable 1: Failure and repair times

Where $\tilde{3}$, $\tilde{4}$, $\tilde{5}$, $\tilde{6}$, $\tilde{8}$, $\overline{10}$, $\overline{15}$, $\overline{20}$, $\overline{25}$, $\overline{30}$, $\overline{35}$, $\overline{45}$ and $\overline{50}$ are vague numbers with the following membership functions

$t_{\overline{3}}(u) = \begin{cases} \frac{u-1}{4} & 1 & u & 3\\ \frac{5-u}{4} & 3 < u & 5 \end{cases}, 1 - f_{\overline{3}}(u) = \begin{cases} \frac{u-1}{2} \\ \frac{5-u}{2} \\ \frac{5-u}{2} \\ \frac{1-1}{2} \\ \frac{5-u}{2} \\ \frac{1-1}{2} \\ 1-$	1	и	3
$\frac{1}{2} \frac{1}{3} \frac{1}{4} - \frac{1}{3} \frac{5-u}{2} - \frac{1}{3} \frac{5-u}{2} - \frac{1}{2} \frac{5-u}{2} - \frac{1}{2} \frac{5-u}{2} - \frac{1}{2} $	3 <	и	5
$\frac{u-2}{4} = 2 + u = 4 + \frac{u-2}{2}$	2	и	4
$\iota_{\widetilde{4}}(u) = \int \frac{6-u}{4} 4 < u 6 \frac{1-f_{\widetilde{4}}(u)}{2} = \int \frac{6-u}{2}$	4 <	u	6
$\frac{u-3}{4}$ 3 u 5 $\frac{u-3}{2}$	3	и	5
$t_{\tilde{5}}(u) = \left\{ \frac{7-u}{4} 5 < u 7 \frac{7-u}{2} \right\}$	5 <	< u	7
$\xi_{\overline{a}}(u) = \begin{cases} \frac{u-4}{4} & 4 \le u \le 6\\ \frac{u-4}{4} & 6 < u \le 8 \end{cases}, 1-f_{\overline{a}}(u) = \begin{cases} \frac{u-4}{2} & 4 \le u \le 6\\ \frac{u-4}{2} & 6 < u \le 8 \end{cases}$			
$t_{\overline{g}}(u) = \begin{cases} \frac{u-s}{4} & 6 \le u \le 8\\ \frac{10-u}{4} & 8 < u \le 10 \end{cases}, 1 - f_{\overline{g}}(u) = \begin{cases} \frac{u-s}{2} & 6 \le u \le 8\\ \frac{10-u}{2} & 8 < u \le 10 \end{cases}$			
$r_{155}(u) = \begin{cases} \frac{u-u}{15} & 5 \le u \le 10\\ \frac{15-u}{10} & 10 < u \le 15 \end{cases}, 1 - f_{55}(u) = \begin{cases} \frac{u-u}{15} & 5 \le u \le 10\\ \frac{15-u}{10} & 10 < u \le 15 \end{cases}$			
$t_{\overline{15}}(u) = \begin{cases} \frac{u-10}{2} & 10 \le u \le 15\\ \frac{32^{-u}}{2} & 10 < u \le 15 \end{cases}, 1 - f_{\overline{15}}(u) = \begin{cases} \frac{u-10}{2} & 10 \le u \le 15\\ \frac{32^{-u}}{2} & 10 < u \le 15 \end{cases}$			
$t_{\overline{a55}}(u) = \begin{cases} \frac{u-15}{2} & 15 \le u \le 20\\ \frac{12-u}{2} & 20 < u \le 25 \end{cases}, 1 - f_{\overline{a55}}(u) = \begin{cases} \frac{u-15}{2} & 15 \le u \le 20\\ \frac{12-u}{2} & 20 < u \le 25 \end{cases}$			
$t_{\overline{x}\overline{y}}(u) = \begin{cases} \frac{u-z_0}{2} & 20 \le u \le 25\\ \frac{z_0-u}{2} & 25 < u \le 30 \end{cases}, 1 - f_{\overline{x}\overline{y}}(u) = \begin{cases} \frac{u-z_0}{2} & 20 \le u \le 25\\ \frac{z_0-u}{2} & 25 < u \le 30 \end{cases}$			
$t_{\overline{s}\overline{5}}(u) = \begin{cases} \frac{u-z_{\overline{5}}}{2} & 25 \le u \le 30\\ \frac{z_{\overline{5}}-u}{2} & 30 < u \le 25 \end{cases}, 1 - f_{\overline{s}\overline{5}}(u) = \begin{cases} \frac{u-z_{\overline{5}}}{2} & 25 \le u \le 30\\ \frac{z_{\overline{5}}-u}{2} & 30 < u \le 25 \end{cases}$			
$t_{\overline{s\overline{s}}}(u) = \begin{cases} \frac{u-z_0}{2} & 30 \le u \le 35\\ \frac{4u-u}{2} & 35 < u \le 40 \end{cases}, 1 - f_{\overline{s\overline{s}}}(u) = \begin{cases} \frac{u-z_0}{2} & 30 \le u \le 35\\ \frac{4u-u}{2} & 35 < u \le 40 \end{cases}$			
$t_{\frac{1}{45}}(u) = \begin{cases} \frac{u-40}{2} & 40 \le u \le 45\\ \frac{y_2-u}{2} & 45 \le u \le 50 \end{cases}, 1 - f_{\frac{1}{45}}(u) = \begin{cases} \frac{u-40}{2} & 40 \le u \le 45\\ \frac{y_2-u}{2} & 45 \le u \le 50 \end{cases}$			
$\begin{array}{c} 4 \\ \hline 5 < u \\ 7 \\ \hline 2 \\ \hline 4 \\ \hline 5 < u \\ \hline 7 \\ \hline 8 \\ \hline$			

Now, we want to obtain the vague Bayesian system reliability and availability. First of all, note that the α_t -cuts and α_f -cuts of the vague numbers 3, 4, 5, 6, 8, 10, 15, 20, 25, 30, 35, 45 and 50 are

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$$\begin{split} \tilde{\mathbf{3}}_{a_t} &= [1 + 4\alpha_t, 5 - 4\alpha_t], \ \tilde{\mathbf{3}}_{a_f} = [1 + 2\alpha_f, 5 - 2\alpha_f] \\ \tilde{\mathbf{4}}_{a_t} &= [2 + 4\alpha_t, 6 - 4\alpha_t], \ \tilde{\mathbf{4}}_{a_f} = [2 + 2\alpha_f, 6 - 2\alpha_f] \\ \tilde{\mathbf{5}}_{a_t} &= [3 + 4\alpha_t, 7 - 4\alpha_t], \ \tilde{\mathbf{5}}_{a_f} = [3 + 2\alpha_f, 7 - 2\alpha_f] \\ \tilde{\mathbf{5}}_{a_t} &= [4 + 4\alpha_t, 8 - 4\alpha_t], \ \tilde{\mathbf{5}}_{a_f} = [4 + 2\alpha_f, 8 - 2\alpha_f] \\ \tilde{\mathbf{5}}_{a_t} &= [6 + 4\alpha_t, 10 - 4\alpha_t], \ \tilde{\mathbf{5}}_{a_f} = [6 + 2\alpha_f, 10 - 2\alpha_f] \\ \tilde{\mathbf{5}}_{a_t} &= [10 + 10\alpha_t, 15 - 10\alpha_t], \ \tilde{\mathbf{15}}_{a_f} = [10 + 5\alpha_f, 20 - 5\alpha_f] \\ \tilde{\mathbf{5}}_{a_t} &= [10 + 10\alpha_t, 20 - 10\alpha_t], \ \tilde{\mathbf{55}}_{a_f} = [10 + 5\alpha_f, 25 - 5\alpha_f] \\ \tilde{\mathbf{55}}_{a_t} &= [10 + 10\alpha_t, 30 - 10\alpha_t], \ \tilde{\mathbf{55}}_{a_f} = [20 + 5\alpha_f, 30 - 5\alpha_f] \\ \tilde{\mathbf{55}}_{a_t} &= [25 + 10\alpha_t, 35 - 10\alpha_t], \ \tilde{\mathbf{55}}_{a_f} = [25 + 5\alpha_f, 35 - 5\alpha_f] \\ \tilde{\mathbf{55}}_{a_t} &= [30 + 10\alpha_t, 40 - 10\alpha_t], \ \tilde{\mathbf{55}}_{a_f} = [40 + 5\alpha_f, 40 - 5\alpha_f] \\ \tilde{\mathbf{55}}_{a_t} &= [40 + 10\alpha_t, 50 - 10\alpha_t], \ \tilde{\mathbf{55}}_{a_f} = [40 + 5\alpha_f, 50 - 5\alpha_f] \\ \tilde{\mathbf{55}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} = [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} &= [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} &= [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} &= [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_f} &= [45 + 5\alpha_f, 55 - 5\alpha_f] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50}}_{a_t} &= [45 + 5\alpha_t, 55 - 5\alpha_t] \\ \tilde{\mathbf{50}}_{a_t} &= [45 + 10\alpha_t, 55 - 10\alpha_t], \ \tilde{\mathbf{50$$

The vague Bayes point estimates of reliability under different loss functions of $\tilde{r}_{\alpha_t}^L$, $\tilde{r}_{\alpha_t}^U$, $\tilde{r}_{\alpha_f}^L$ and $\tilde{r}_{\alpha_f}^U$ are obtained as follows (for all α_t , $\alpha_f = [0, 1]$)

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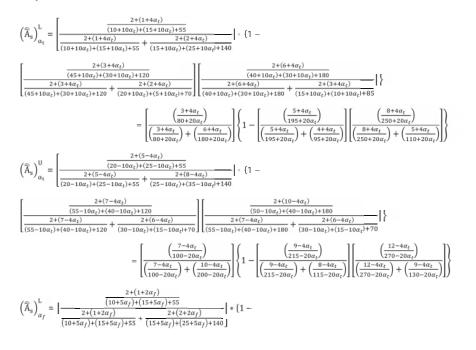
$$\left(1 - \frac{(50 - 10\alpha_f) + (40 - 10\alpha_f) + 180}{(50 - 10\alpha_f) + (40 - 10\alpha_f) + 180 + 30}\right)^{2 + (10 - 2\alpha_f)} = \left|\frac{220 - 10\alpha_f}{250 - 10\alpha_f}\right|^{10 - 2\alpha_f} \left[1 - \left(\frac{30}{245 - 10\alpha_f}\right)^{9 - 2\alpha_f} \left(\frac{30}{300 - 10\alpha_f}\right)^{12 - 2\alpha_f}\right]$$

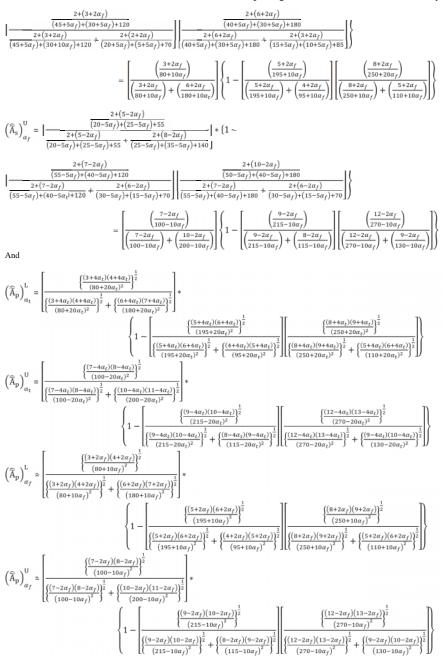
And

$$\left(\hat{f}_{\mathrm{P}} \right)_{\alpha_{t}}^{L} = \left| \frac{\left(180 + 20\alpha_{t} \right)}{\left(220 + 20\alpha_{t} \right)} \right|^{6+4\alpha_{t}} \left\{ 1 - 2\left(\frac{30}{225 + 20\alpha_{t}} \right)^{5+4\alpha_{t}} \left(\frac{30}{280 + 20\alpha_{t}} \right)^{8+4\alpha_{t}} + \left| 1 - 2\left(\frac{195 + 20\alpha_{t}}{225 + 20\alpha_{t}} \right)^{5+4\alpha_{t}} \left(\frac{195 + 20\alpha_{t}}{255 + 20\alpha_{t}} \right)^{5+4\alpha_{t}} \right] \left[1 - 2\left(\frac{250 + 20\alpha_{t}}{280 + 20\alpha_{t}} \right)^{8+4\alpha_{t}} \left(\frac{250 + 20\alpha_{t}}{310 + 20\alpha_{t}} \right)^{8+4\alpha_{t}} \right]^{\frac{1}{2}}$$

$$\begin{split} \left(\hat{\hat{r}}_{\rm p}\right)_{a_{t}}^{U} &= \left|\frac{\left(220-20\alpha_{t}\right)}{\left(220+20\alpha_{t}\right)}\right|^{10-4\alpha_{t}} \left\{1-2\left\{\frac{30}{245-20\alpha_{t}}\right\}^{9-4\alpha_{t}}\left(\frac{30}{300-20\alpha_{t}}\right)^{12-4\alpha_{t}} \left(\frac{270-20\alpha_{t}}{300-20\alpha_{t}}\right)^{12-4\alpha_{t}}\right. \\ &+ \left|1-2\left\{\frac{215-20\alpha_{t}}{245-20\alpha_{t}}\right\}^{9-4\alpha_{t}}\left(\frac{215-20\alpha_{t}}{275-20\alpha_{t}}\right)^{9-4\alpha_{t}}\right] \left[1-2\left\{\frac{270-20\alpha_{t}}{300-20\alpha_{t}}\right\}^{12-4\alpha_{t}}\left(\frac{270-20\alpha_{t}}{330-20\alpha_{t}}\right)^{12-4\alpha_{t}}\right] \right\}^{\frac{1}{2}} \\ \left(\hat{\hat{r}}_{\rm p}\right)_{a_{f}}^{L} &= \left[\frac{\left(180+10\alpha_{f}\right)}{\left(220+10\alpha_{f}\right)}\right]^{6+2\alpha_{f}} \left\{1-2\left\{\frac{30}{225+10\alpha_{f}}\right\}^{5+2\alpha_{f}}\left\{\frac{30}{280+10\alpha_{f}}\right\}^{8+2\alpha_{f}} \left(\frac{30}{280+10\alpha_{f}}\right)^{8+2\alpha_{f}} \left(\frac{250+10\alpha_{f}}{310+10\alpha_{f}}\right)^{8+2\alpha_{f}}\right] \\ &+ \left|1-2\left\{\frac{195+10\alpha_{f}}{225+10\alpha_{f}}\right\}^{5+2\alpha_{f}}\left(\frac{195+10\alpha_{f}}{255+10\alpha_{f}}\right)^{5+2\alpha_{f}}\right] \left[1-2\left(\frac{250+10\alpha_{f}}{280+10\alpha_{f}}\right)^{8+2\alpha_{f}}\left(\frac{250+10\alpha_{f}}{310+10\alpha_{f}}\right)^{8+2\alpha_{f}}\right] \\ &+ \left|1-2\left\{\frac{30}{245-10\alpha_{f}}\right\}^{9-2\alpha_{f}}\left\{\frac{30}{300-10\alpha_{f}}\right\}^{9-2\alpha_{f}}\left(\frac{30}{300-10\alpha_{f}}\right)^{12-2\alpha_{f}} \left(\frac{270-10\alpha_{f}}{330-10\alpha_{f}}\right)^{12-2\alpha_{f}} \right] \\ &+ \left|1-2\left\{\frac{215-10\alpha_{f}}{245-10\alpha_{f}}\right\}^{9-2\alpha_{f}}\left(\frac{215-10\alpha_{f}}{275-10\alpha_{f}}\right)^{9-2\alpha_{f}}\right\} \left[1-2\left(\frac{270-10\alpha_{f}}{300-10\alpha_{f}}\right)^{12-2\alpha_{f}} \left(\frac{270-10\alpha_{f}}{300-10\alpha_{f}}\right)^{12-2\alpha_{f}} \right] \\ &+ \left|1-2\left[\frac{215-10\alpha_{f}}{245-10\alpha_{f}}\right]^{9-2\alpha_{f}} \left(\frac{215-10\alpha_{f}}{275-10\alpha_{f}}\right)^{9-2\alpha_{f}} \left(\frac{215-10\alpha_{f}}{300-10\alpha_{f}}\right)^{12-2\alpha_{f}} \left(\frac{270-10\alpha_{f}}{300-10\alpha_{f}}\right)^{12-2\alpha_{f}} \right] \\ &+ \left|1-2\left[\frac{215-10\alpha_{f}}{245-10\alpha_{f}}\right]^{9-2\alpha_{f}} \left(\frac{215-10\alpha_{f}}{275-10\alpha_{f}}\right)^{9-2\alpha_{f}} \left(\frac{215-10\alpha_{f}}{300-10\alpha_{f}}\right)^{12-2\alpha_{f}} \left(\frac{215-10\alpha_{f}}{30-10\alpha_{f}}\right)^{12-2\alpha_{f}} \left(\frac{215-10\alpha_{f}}{30-10\alpha_{f}}\right)^{12-2\alpha_{f}} \left(\frac{215-10\alpha_{f}$$

The vague Bayes point estimates of availability under different loss functions of $\tilde{A}_{\alpha_t}^L$, $\tilde{A}_{\alpha_t}^U$, $\tilde{A}_{\alpha_f}^L$ and $\tilde{A}_{\alpha_f}^U$ are obtained as follows (for all α_t , α_f [0, 1])





Therefore, we just need to solve subproblems II_T and II_F . We use the method provided in Section 5 to solve these problems. For $\alpha_t = 0.5$ yields $(\hat{r}_s)_{0.5}^L = (\frac{190}{230})^8 \left[1 - (\frac{30}{235})^7 (\frac{30}{290})^{10}\right] = 0.21687 = (\hat{r}_s)_{0.5}^U$, i.e. $t_{\hat{r}}(0.21687) = 0.5$. on the other hand, $z_f = 1$ yields $(\hat{r}_s)_1^L = 0.21687 = (\hat{r}_s)_1^U$, i.e. $1 - f_{\hat{r}}(0.21687) = 1$. Since $V_0 = [0.27851, 0.29998]$, we are just interested in considering the system reliability $r = V_0$. By

applying the Supplemental Procedure Wu (2004), we have, for $r = V_0$.

(i) if r < 0.21687, then we solve the following problem, using a suitable software (LINGO): $t_{i}(r)$

$$= \max \left\{ \alpha_t \in [0, 1] : g(\alpha_t) = g_1(\alpha_t) = \left(\hat{r}_s\right)_{\alpha_t}^L \right.$$

$$= \left| \frac{180 + 20\alpha_t}{220 + 20\alpha_t} \right|^{6+4\alpha_t} \left[1 - \left(\frac{30}{225 + 20\alpha_t}\right)^{5+4\alpha_t} \left(\frac{30}{280 + 20\alpha_t}\right)^{8+4\alpha_t} \right] : r \right\}$$

$$= \max \left\{ \alpha_f \in [0, 1] : g(\alpha_f) = g_1(\alpha_f) = \left(\hat{r}_s\right)_{\alpha_f}^L \right.$$

$$= \left| \frac{180 + 10}{220 + 20} :_f \right|^{6+2\alpha_f} \left[1 - \left(\frac{30}{225 + 10} :_f\right)^{5+2\alpha_t} \left(\frac{30}{280 + 10} :_f\right)^{8+2\alpha_f} \right] : \left\{ \right\}$$

(ii) if r > 0.21687, then we solve the following problem:

$$\begin{split} t_{\hat{p}}(r) &= max \Big\{ \alpha_t \in [0,1] : g(\alpha_t) = g_1(\alpha_t) = \left(\widehat{r_s} \right)_{\alpha_t}^L \\ &= \Big| \frac{180 + 20\alpha_t}{220 + 20\alpha_t} \Big|^{6+4\alpha_t} \Big[1 - \left(\frac{30}{225 + 20\alpha_t} \right)^{5+4\alpha_t} \left(\frac{30}{280 + 20\alpha_t} \right)^{8+4\alpha_t} \Big] : r \Big\} \\ 1 - f_{\hat{p}}(r) &= max \Big\{ \alpha_f \in [0,1] : g(\alpha_f) = g_1(\alpha_f) = \left(\widehat{r_s} \right)_{\alpha_f}^L = \Big[\frac{180 + 20\alpha_t}{220 + 20\alpha_t} \Big]^{6+4\alpha_t} \Big[1 - \left(\frac{30}{225 + 20\alpha_t} \right)^{5+4\alpha_t} \left(\frac{30}{280 + 20\alpha_t} \right)^{8+4\alpha_t} \Big] : r \Big\} \end{split}$$

Therefore we now can obtain the membership degree for any given Bayes point estimate r of vague system reliability \tilde{r} by evaluating the above formulas.

Above conclusion is defined by the same way for system availability.

6. Conclusion

We developed Bayesian approach to system reliability analysis in the vague environment, Taheri and Zarei (2011), for system availability under different loss function based on Exponential distribution. In order to evaluate the truth and false membership degrees of the vague Bayes estimate, a nonlinear programming problem was solved. The vague Bayesian approach to system reliability and availability is a generalized version of the fuzzy Bayesian reliability and availability, and it is also an extension of the conventional Bayesian system reliability and availability.

For future research, distributions other than exponential distribution can be used for failure and repair times of system. In addition to vague data in the analysis, vague multi state reli- reliability can be considered.

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